

Definition 110. Let A be $n \times n$. The **matrix exponential** is

$$e^A = I + A + \frac{1}{2!}A^2 + \frac{1}{3!}A^3 + \dots$$

Why? As a consequence of this definition (which is the motivation for that definition in the first place),

$$\begin{aligned} \frac{d}{dt}e^{At} &= \frac{d}{dt}\left[I + At + \frac{1}{2!}A^2t^2 + \frac{1}{3!}A^3t^3 + \dots\right] \\ &= 0 + A + A^2t + \frac{1}{2!}A^3t^2 + \dots = Ae^{At}. \end{aligned}$$

Therefore, $\mathbf{y}(t) = e^{At}\mathbf{y}_0$ indeed solves the initial value problem $\mathbf{y}' = A\mathbf{y}$, $\mathbf{y}(0) = \mathbf{y}_0$.

How to actually compute e^A ? Well, this Taylor series involves the powers A^n of A . How would you compute, say, A^{100} ? The answer is diagonalization!

Theorem 111. Suppose $A = PDP^{-1}$. Then, $e^A = Pe^DP^{-1}$.

Why? Recall that, if $A = PDP^{-1}$, then $A^n = PD^nP^{-1}$.

$$\begin{aligned} e^A &= I + A + \frac{1}{2!}A^2 + \frac{1}{3!}A^3 + \dots \\ &= I + PDP^{-1} + \frac{1}{2!}PD^2P^{-1} + \frac{1}{3!}PD^3P^{-1} + \dots \\ &= P\left(I + D + \frac{1}{2!}D^2 + \frac{1}{3!}D^3 + \dots\right)P^{-1} = Pe^DP^{-1} \end{aligned}$$

Comment. By the same argument, if $A = PDP^{-1}$, then $f(A) = Pf(D)P^{-1}$ for any “nice” function f . Here, “nice” means that f has a convergent Taylor series $f(x) = \sum_{n \geq 0} a_n x^n$.

More explicitly, if $A = P \operatorname{diag}(\lambda_1, \dots, \lambda_n) P^{-1}$, then $f(A) = P \operatorname{diag}(f(\lambda_1), \dots, f(\lambda_n)) P^{-1}$.

Example 112. If $A = \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix}$, then $A^{100} = \begin{bmatrix} 2^{100} & 0 \\ 0 & 5^{100} \end{bmatrix}$.

Example 113. If $A = \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix}$, then $e^A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix} + \frac{1}{2!} \begin{bmatrix} 2^2 & 0 \\ 0 & 5^2 \end{bmatrix} + \dots = \begin{bmatrix} e^2 & 0 \\ 0 & e^5 \end{bmatrix}$.

Clearly, this works to obtain e^D for any diagonal matrix D .

In particular, for $At = \begin{bmatrix} 2t & 0 \\ 0 & 5t \end{bmatrix}$, $e^{At} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 2t & 0 \\ 0 & 5t \end{bmatrix} + \frac{1}{2!} \begin{bmatrix} (2t)^2 & 0 \\ 0 & (5t)^2 \end{bmatrix} + \dots = \begin{bmatrix} e^{2t} & 0 \\ 0 & e^{5t} \end{bmatrix}$.

Example 114. (homework) Diagonalize $A = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$.

Solution. (final solution only) $A = PDP^{-1}$ with $P = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ and $D = \begin{bmatrix} 2 & & \\ & 2 & \\ & & 4 \end{bmatrix}$.

Example 115. Solve the initial value problem

$$\mathbf{y}' = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix} \mathbf{y}, \quad \mathbf{y}(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}.$$

Solution. Recall that the solution to $\mathbf{y}' = A\mathbf{y}$, $\mathbf{y}(0) = \mathbf{y}_0$ is $\mathbf{y} = e^{At}\mathbf{y}_0$.

- For $A = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$, $A = PDP^{-1}$ with $P = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ and $D = \begin{bmatrix} 2 & & \\ & 2 & \\ & & 4 \end{bmatrix}$. (That's homework!)
- Compute the solution $\mathbf{y} = e^{At}\mathbf{y}_0$:

$$\begin{aligned} \mathbf{y} = e^{At}\mathbf{y}_0 &= Pe^{Dt}P^{-1}\mathbf{y}_0 \\ &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} e^{2t} & & \\ & e^{2t} & \\ & & e^{4t} \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} e^{2t} & & \\ & e^{2t} & \\ & & e^{4t} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} e^{2t} \\ 0 \\ e^{4t} \end{bmatrix} = \begin{bmatrix} e^{2t} \\ e^{2t} + e^{4t} \\ e^{4t} \end{bmatrix} \end{aligned}$$

Comment. It is not necessary to compute $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1}$ (of course, you could do it, but that's more work).

Instead, recall that $A^{-1}\mathbf{b}$ is the unique solution to $A\mathbf{x} = \mathbf{b}$. Here, solving $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, we find $\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.

Check. $\mathbf{y} = \begin{bmatrix} e^{2t} \\ e^{2t} + e^{4t} \\ e^{4t} \end{bmatrix}$ indeed solves the original problem:

$$\mathbf{y}' = \begin{bmatrix} 2e^{2t} \\ 2e^{2t} + 4e^{4t} \\ 4e^{4t} \end{bmatrix} \stackrel{\checkmark}{=} \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix} \begin{bmatrix} e^{2t} \\ e^{2t} + e^{4t} \\ e^{4t} \end{bmatrix}, \quad \mathbf{y}(0) = \begin{bmatrix} 1 \\ 1+1 \\ 1 \end{bmatrix} \stackrel{\checkmark}{=} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$