

Please print your name:

Computational part

Problem 1. Evaluate the following determinants.

[Real computations only necessary for the last two.]

$$(a) \begin{vmatrix} 1 & 1 & 4 \\ 2 & 2 & 5 \\ 3 & 3 & 6 \end{vmatrix}$$

$$(d) \begin{vmatrix} 1 & 2 & -2 & 0 \\ 2 & 3 & -4 & 0 \\ -1 & -2 & 0 & 0 \\ 0 & 2 & 5 & 0 \end{vmatrix}$$

$$(b) \begin{vmatrix} 1 & 1 & 4 \\ 0 & 2 & 5 \\ 0 & 0 & 6 \end{vmatrix}$$

$$(e) \begin{vmatrix} 1 & 2 & 3 \\ 1 & 1 & 3 \\ 3 & 2 & 1 \end{vmatrix}$$

$$(c) \begin{vmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \end{vmatrix}$$

$$(f) \begin{vmatrix} 1 & 2 & -2 & 0 \\ 2 & 3 & -4 & 1 \\ -1 & -2 & 0 & 2 \\ 0 & 2 & 5 & 3 \end{vmatrix}$$

Solution.

$$(a) \begin{vmatrix} 1 & 1 & 4 \\ 2 & 2 & 5 \\ 3 & 3 & 6 \end{vmatrix} = 0 \text{ because the columns are not linearly independent. (Column one and two are the same.)}$$

$$(b) \begin{vmatrix} 1 & 1 & 4 \\ 0 & 2 & 5 \\ 0 & 0 & 6 \end{vmatrix} = 1 \cdot 2 \cdot 6 = 12$$

$$(c) \begin{vmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \end{vmatrix} = (-1)(-1)(-1) = -1 \text{ because it takes three row interchanges } (R_1 \Leftrightarrow R_6, R_2 \Leftrightarrow R_5, R_3 \Leftrightarrow R_4)$$

to transform this matrix to the 6×6 identity matrix.

$$(d) \begin{vmatrix} 1 & 2 & -2 & 0 \\ 2 & 3 & -4 & 0 \\ -1 & -2 & 0 & 0 \\ 0 & 2 & 5 & 0 \end{vmatrix} = 0 \text{ because the matrix is clearly not invertible. (Look at the last column!)}$$

$$(e) \begin{vmatrix} 1 & 2 & 3 \\ 1 & 1 & 3 \\ 3 & 2 & 1 \end{vmatrix} \begin{matrix} R_2 - R_1 \Rightarrow R_2 \\ R_3 - 3R_1 \Rightarrow R_3 \\ = \end{matrix} \begin{vmatrix} 1 & 2 & 3 \\ 0 & -1 & 0 \\ 0 & -4 & -8 \end{vmatrix} \begin{matrix} R_3 - 4R_2 \Rightarrow R_3 \\ = \end{matrix} \begin{vmatrix} 1 & 2 & 3 \\ 0 & -1 & 0 \\ 0 & 0 & -8 \end{vmatrix} = 1 \cdot (-1) \cdot (-8) = 8$$

$$(f) \left| \begin{array}{cccc|ccc} 1 & 2 & -2 & 0 & R_2 - 2R_1 \Rightarrow R_2 & 1 & 2 & -2 & 0 \\ 2 & 3 & -4 & 1 & R_3 + R_1 \Rightarrow R_3 & 0 & -1 & 0 & 1 \\ -1 & -2 & 0 & 2 & & 0 & 0 & -2 & 2 \\ 0 & 2 & 5 & 3 & & 0 & 2 & 5 & 3 \end{array} \right| \xrightarrow{R_4 + 2R_2 \Rightarrow R_4} \left| \begin{array}{cccc|ccc} 1 & 2 & -2 & 0 & & 1 & 2 & -2 & 0 \\ 0 & -1 & 0 & 1 & & 0 & -1 & 0 & 1 \\ 0 & 0 & -2 & 2 & & 0 & 0 & -2 & 2 \\ 0 & 0 & 5 & 5 & & 0 & 0 & 5 & 5 \end{array} \right| \xrightarrow{R_4 + \frac{5}{2}R_3 \Rightarrow R_4} \left| \begin{array}{cccc|ccc} 1 & 2 & -2 & 0 & & 1 & 2 & -2 & 0 \\ 0 & -1 & 0 & 1 & & 0 & -1 & 0 & 1 \\ 0 & 0 & -2 & 2 & & 0 & 0 & -2 & 2 \\ 0 & 0 & 0 & 10 & & 0 & 0 & 0 & 10 \end{array} \right|$$

$$= 1 \cdot (-1) \cdot (-2) \cdot 10 = 20$$

□

Problem 2. Find a basis for $\text{col}(A)$, $\text{row}(A)$, $\text{null}(A)$ with

$$(a) A = \begin{bmatrix} 1 & 2 & 1 & 1 & 5 \\ -1 & -2 & -1 & -1 & -3 \\ 2 & 4 & 0 & -6 & 7 \end{bmatrix}$$

$$(b) A = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$(c) A = [1 \ 2 \ 3]$$

Solution.

- (a) Our first step is to bring A into RREF (just an echelon form would be enough, but then we would need to back-substitute when solving $A\mathbf{x} = \mathbf{0}$ for $\text{null}(A)$):

$$\left[\begin{array}{ccccc} 1 & 2 & 1 & 1 & 5 \\ -1 & -2 & -1 & -1 & -3 \\ 2 & 4 & 0 & -6 & 7 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{ccccc} 1 & 2 & 0 & -3 & 0 \\ 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right] \begin{array}{l} \text{do} \\ \text{it!} \end{array}$$

- A basis for $\text{col}(A)$ is: $\left[\begin{array}{c} 1 \\ -1 \\ 2 \end{array} \right], \left[\begin{array}{c} 1 \\ -1 \\ 0 \end{array} \right], \left[\begin{array}{c} 5 \\ -3 \\ 7 \end{array} \right]$. ($\dim \text{col}(A) = 3$)

- A basis for $\text{row}(A)$ is: $\left[\begin{array}{c} 1 \\ 2 \\ 0 \\ -3 \\ 0 \end{array} \right], \left[\begin{array}{c} 0 \\ 0 \\ 1 \\ 4 \\ 0 \end{array} \right], \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{array} \right]$. ($\dim \text{row}(A) = 3$)

- $x_2 = s_1$ and $x_4 = s_2$ are our free variables. The general solution to $A\mathbf{x} = \mathbf{0}$ is:

$$\mathbf{x} = \begin{bmatrix} -2s_1 + 3s_2 \\ s_1 \\ -4s_2 \\ s_2 \\ 0 \end{bmatrix} = s_1 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s_2 \begin{bmatrix} 3 \\ 0 \\ -4 \\ 1 \\ 0 \end{bmatrix}$$

Hence, $\left[\begin{array}{c} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{array} \right], \left[\begin{array}{c} 3 \\ 0 \\ -4 \\ 1 \\ 0 \end{array} \right]$ is a basis for $\text{null}(A)$. ($\dim \text{null}(A) = 2$)

- (b) A basis for $\text{col}(A)$ is: $\left[\begin{array}{c} 1 \\ 2 \\ 3 \end{array} \right]$.

A basis for $\text{row}(A)$ is: $[1]$.

$\text{null}(A) = \{[0]\}$ (only the trivial solution), which has dimension 0 and therefore a basis with 0 vectors (that is, a/the basis is the empty set \emptyset).

(c) A basis for $\text{col}(A)$ is: $[1]$.

A basis for $\text{row}(A)$ is: $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$.

The general solution to $A\mathbf{x} = \mathbf{0}$ is (note that A is in RREF already) $\mathbf{x} = \begin{bmatrix} -2s_1 - 3s_2 \\ s_1 \\ s_2 \end{bmatrix} = s_1 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + s_2 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$.

Hence, a basis for $\text{null}(A)$ is: $\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$. □

Problem 3.

(a) Is $W = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} : a - b = c, a - d = e \right\}$ a vector space? If yes, find a basis.

(b) Is $W = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$ a vector space? If yes, find a basis.

(c) Is $W = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$ a vector space? If yes, find a basis.

(d) Is $W = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$ a vector space? If yes, find a basis.

Solution.

(a) The matrix form of the linear equations $a - b = c, a - d = e$ is $\begin{bmatrix} 1 & -1 & -1 & 0 & 0 \\ 1 & 0 & 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

This means that $W = \text{null}\left(\begin{bmatrix} 1 & -1 & -1 & 0 & 0 \\ 1 & 0 & 0 & -1 & -1 \end{bmatrix}\right)$.

$$\begin{bmatrix} 1 & -1 & -1 & 0 & 0 \\ 1 & 0 & 0 & -1 & -1 \end{bmatrix} \xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & -1 & -1 & 0 & 0 \\ 0 & 1 & 1 & -1 & -1 \end{bmatrix} \xrightarrow{R_1 + R_2} \begin{bmatrix} 1 & 0 & 0 & -1 & -1 \\ 0 & 1 & 1 & -1 & -1 \end{bmatrix}$$

The general solution of our system is $\begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} = \begin{bmatrix} s_2 + s_3 \\ -s_1 + s_2 + s_3 \\ s_1 \\ s_2 \\ s_3 \end{bmatrix} = s_1 \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + s_2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + s_3 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$.

A basis for W is $\begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$.

(b) Yes, W is a vector space. It has dimension 0 and therefore a basis with 0 vectors (that is, a/the basis is the empty set \emptyset).

(c) No, W is not a vector space, because $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \notin W$.

(d) No, W is not a vector space. For instance, it contains $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ but not $-1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. □

Problem 4. Consider $H = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}\right\}$.

- (a) Give a basis for H . What is the dimension of H ?
- (b) Determine whether the vector $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is in H . What about the vector $\begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$?
- (c) Extend the basis of H to a basis of \mathbb{R}^3 .

Solution.

(a) Clearly, $H = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}\right\}$.

Moreover, $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ are a basis for H (because these two vectors are linearly independent).

In particular, $\dim H = 2$.

(b) We need to solve $\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 0 & 1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 0 & 1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$.

Let us do both at the same time (by working with two right-hand sides at once):

$$\left[\begin{array}{cc|cc} 1 & 1 & 1 & 1 \\ 1 & 2 & 0 & 3 \\ 0 & 1 & 0 & 2 \end{array} \right] \xrightarrow{R_2 - R_1} \left[\begin{array}{cc|cc} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 1 & 0 & 2 \end{array} \right] \xrightarrow{R_3 - R_2} \left[\begin{array}{cc|cc} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

The first equation is inconsistent and so $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is not in H .

The first equation is consistent and so $\begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$ is in H .

(c) We need to add a third vector to our basis $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ of H . In the previous part, we found that $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is not in H .

In other words, $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ are linearly independent.

It follows that $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ are a basis for \mathbb{R}^3 . □

Problem 5. Is it true that $\text{span}\left\{\begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -2 \\ 0 \\ 1 \end{bmatrix}\right\} = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix}\right\}$?

Solution. Let $V = \text{span}\left\{\begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -2 \\ 0 \\ 1 \end{bmatrix}\right\}$ and $W = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix}\right\}$.

We check that $\begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix} \in V$ and $\begin{bmatrix} 2 \\ 0 \\ 2 \\ -1 \end{bmatrix} \in V$.

(This follows, as in the previous problem, from $\left[\begin{array}{cc|cc} 1 & 0 & 1 & 2 \\ -1 & -2 & 1 & 0 \\ 1 & 0 & 1 & 2 \\ 0 & 1 & -1 & -1 \end{array} \right] \xrightarrow[\sim]{\begin{array}{l} R_2+R_1 \Rightarrow R_2 \\ R_3-R_1 \Rightarrow R_3 \end{array}} \left[\begin{array}{cc|cc} 1 & 0 & 1 & 2 \\ 0 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & -1 \end{array} \right] \xrightarrow[\sim]{R_4+\frac{1}{2}R_2 \Rightarrow R_4} \left[\begin{array}{cc|cc} 1 & 0 & 1 & 2 \\ 0 & -2 & 2 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$,
because for both right-hand sides the system is consistent.)

Since these two vectors span W , this implies that W is a subspace of V .

But both spaces have dimension 2, and so they must be equal: $V = W$. □

Short answer part

Problem 6. Let A be a 5×4 matrix. Suppose that the linear system $A\mathbf{x} = \mathbf{b}$ has the solution set

$$\left\{ \begin{bmatrix} 1 - c + d \\ c \\ 3 - 2d \\ d \end{bmatrix} : c, d \text{ in } \mathbb{R} \right\}.$$

- (a) Give a basis for the null space of A .
- (b) What is the rank of A ?

Solution.

(a) Observe that $\begin{bmatrix} 1 - c + d \\ c \\ 3 - 2d \\ d \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 3 \\ 0 \end{bmatrix} + c \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$.

Here, $\begin{bmatrix} 1 \\ 0 \\ 3 \\ 0 \end{bmatrix}$ is a particular solution to $A\mathbf{x} = \mathbf{b}$ and $c \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$ is the general solution to $A\mathbf{x} = \mathbf{0}$.

In particular, $\begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$ are a basis for $\text{null}(A)$.

- (b) $\text{rank}(A) = 4 - 2 = 2$ because A has 4 columns and we know that 2 of them correspond to free variables. □

Problem 7. In each case, write down a precise definition or answer.

- (a) What is a vector space?
- (b) What is the rank of a matrix?
- (c) What does it mean for vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ from a vector space to be linearly independent?
- (d) List the elementary row operations.
- (e) What does it mean for vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ to be a basis for a vector space V ?

Solution.

- (a) A vector space is a set V of vectors that can be written as a span (that is, $V = \text{span}\{\mathbf{w}_1, \mathbf{w}_2, \dots\}$ for a bunch of vectors $\mathbf{w}_1, \mathbf{w}_2, \dots$).

An alternative, more abstract, definition is: A vector space is a set V of vectors such that

- if $\mathbf{v}, \mathbf{w} \in V$, then $\mathbf{v} + \mathbf{w} \in V$, [closed under addition]
- if $\mathbf{v} \in V$ and $r \in \mathbb{R}$, then $r\mathbf{v} \in V$. [closed under scalar multiplication]

- (b) The rank of a matrix is the number of pivots in an echelon form.

Alternatively: The rank of a matrix is the dimension of its column space. (Or, row space.)

- (c) Vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are linearly independent if the only solution to

$$x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \dots + x_n\mathbf{v}_n = \mathbf{0}$$

is the trivial one ($x_1 = x_2 = \dots = x_n = 0$).

- (d) The elementary row operations are:

- (*replacement*) $R_j - \lambda R_i \Rightarrow R_j$
- (*swap two rows*) $R_j \Leftrightarrow R_i$
- (*scaling*) $\lambda R_i \Rightarrow R_i$

- (e) The vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are a basis for V , if $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly independent and $V = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$.

□

Problem 8. Let A be a $n \times n$ matrix. List at least five other statements which are equivalent to the statement “ A is invertible”.

Solution. Here are a few possibilities:

A is invertible.

\Leftrightarrow The RREF of A is I_n .

\Leftrightarrow A has n pivots.

\Leftrightarrow $\text{rank}(A) = n$

\Leftrightarrow For every $\mathbf{b} \in \mathbb{R}^n$, the system $A\mathbf{x} = \mathbf{b}$ has a unique solution.

\Leftrightarrow The system $A\mathbf{x} = \mathbf{0}$ has a unique solution.

\Leftrightarrow $\dim \text{null}(A) = 0$

\Leftrightarrow The columns of A are linearly independent.

\Leftrightarrow The rows of A are linearly independent.

\Leftrightarrow For every $\mathbf{b} \in \mathbb{R}^n$, the system $A\mathbf{x} = \mathbf{b}$ has a solution.

\Leftrightarrow The columns of A span all of \mathbb{R}^n .

\Leftrightarrow $\dim \text{col}(A) = n$

\Leftrightarrow The rows of A span all of \mathbb{R}^n .

\Leftrightarrow $\dim \text{row}(A) = n$

\Leftrightarrow $\det(A) \neq 0$

□

Problem 9.

- (a) Suppose V and W are subspaces of \mathbb{R}^n , and that $\mathbf{v}_1, \mathbf{v}_2$ is a basis for V , and $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$ is a basis for W . What can you say about $\dim U$ with $U = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$?
- (b) Let A be a 4×3 matrix, whose row space has dimension 2. What is the dimension of $\text{null}(A)$?
- (c) Let A be a 3×3 matrix, whose column space has dimension 3. If \mathbf{b} is a vector in \mathbb{R}^3 , what can you say about the number of solutions to the equation $A\mathbf{x} = \mathbf{b}$?
- (d) Let A be a 3×3 matrix, whose column space has dimension 2. What can you say about $\det(A)$?

Solution.

- (a) $\dim U \in \{3, 4, 5\}$
- (b) $\dim \text{null}(A) = 3 - 2 = 1$
- (c) If A is a 3×3 matrix, whose column space has dimension 3, then A is invertible.
Therefore, the equation $A\mathbf{x} = \mathbf{b}$ has a unique solution for any \mathbf{b} .
- (d) If A is a 3×3 matrix, whose column space has dimension 2, then A is not invertible.
Therefore, $\det(A) = 0$. □

Problem 10. True or false?

- (a) Every vector space has a basis.
- (b) The zero vector can never be a basis vector.
- (c) Every set of linearly independent vectors in V can be extended to a basis of V .
- (d) $\text{col}(A)$ and $\text{row}(A)$ always have the same dimension.
- (e) If B is the RREF of A , then we always have $\text{col}(A) = \text{col}(B)$.
- (f) If B is the RREF of A , then we always have $\text{row}(A) = \text{row}(B)$.
- (g) If a subspace V of \mathbb{R}^3 contains three linearly independent vectors, then always $V = \mathbb{R}^3$.
- (h) There are matrices A such that $\text{null}(A)$ is the empty set.

Solution.

- (a) True. In fact, for all the spaces we can get our hands on, we know how to compute a basis.
[In the case of very infinite-dimensional spaces, this becomes “the axiom of choice”.]
- (b) True. A set of vector that includes the zero vector can never be linearly independent.
- (c) True. We just keep adding missing vectors from V to the initial set of linearly independent vectors until we span all of V . (If V has dimension d , then this process of adding vectors has to stop once we have a total of d vectors.)
- (d) True.
- (e) False. Elementary row operations do not preserve column spaces (except by accident).
For instance, $\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ but $\text{col}\left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\right) \neq \text{col}\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right)$.
- (f) True. Elementary row operations do preserve the row space.
- (g) True. Three linearly independent vectors in \mathbb{R}^3 automatically form a basis of \mathbb{R}^3 .
- (h) False. $\text{null}(A)$ always contains at least the zero vector (the trivial solution to $A\mathbf{x} = \mathbf{0}$). □