

Preparation problems for the discussion sections on October 14th and 16th

1. Let $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. Find the length of \mathbf{v} . Find a vector \mathbf{u} in the direction of \mathbf{v} that has length 1. Find a vector \mathbf{w} that is orthogonal to \mathbf{v} .

Solution: The length of \mathbf{v} is $\sqrt{1^2 + 1^2} = \sqrt{2}$. Since $\mathbf{u} = a\mathbf{v}$, we have to find a so that length of \mathbf{u} is 1. So:

$$\sqrt{a^2 + a^2} = 1$$

Thus, $a = \frac{1}{\sqrt{2}}$ and we have:

$$\mathbf{u} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

For a vector \mathbf{y} orthogonal to \mathbf{v} , we need to find $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$ such that

$$0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = y_1 + y_2$$

One pair y_1, y_2 that satisfies the equation is 1, -1. So the vector $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is orthogonal to \mathbf{v} .

2. Let $\mathbf{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$, and $\mathbf{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$. Find real numbers c_1, c_2 such that

$$\mathbf{v} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2.$$

Solution: Since \mathbf{u}_1 and \mathbf{u}_2 are orthogonal (i.e. $\mathbf{u}_1 \cdot \mathbf{u}_2 = 0$), we have that if

$$\mathbf{v} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2.$$

for some real number c_1, c_2 , then

$$\mathbf{u}_1 \cdot \mathbf{v} = c_1\mathbf{u}_1 \cdot \mathbf{u}_1 + c_2\mathbf{u}_1 \cdot \mathbf{u}_2 = c_1\mathbf{u}_1 \cdot \mathbf{u}_1$$

and

$$\mathbf{u}_2 \cdot \mathbf{v} = c_1\mathbf{u}_2 \cdot \mathbf{u}_1 + c_2\mathbf{u}_2 \cdot \mathbf{u}_2 = c_2\mathbf{u}_2 \cdot \mathbf{u}_2.$$

Hence

$$c_1 = \frac{\mathbf{u}_1 \cdot \mathbf{v}}{\mathbf{u}_1 \cdot \mathbf{u}_1} = \frac{\begin{bmatrix} 2 \\ 3 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}}{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}} = \frac{5}{\sqrt{2}}.$$

and

$$c_2 = \frac{\mathbf{u}_2 \cdot \mathbf{v}}{\mathbf{u}_2 \cdot \mathbf{u}_2} = \frac{\begin{bmatrix} 2 \\ 3 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}}{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}} = \frac{-1}{\sqrt{2}}.$$

(Note: you can also solve the system

$$x_1\mathbf{u}_1 + x_2\mathbf{u}_2 = \mathbf{v},$$

to find the same answer. But observe that the above approach becomes much simpler if you are working with n orthogonal vectors in \mathbb{R}^n .)

3. Let $V = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} : a + b + c + d = 0 \right\}$ be a subspace of \mathbb{R}^4 .

- (a) Find a basis for V .
 (b) Find a vector that is orthogonal to V .
 (c) Can you find two linearly independent vectors that are orthogonal to V ?

Solution:

(a) We have:

$$V = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} : a = -b - c - d \right\} = \left\{ \begin{bmatrix} -b - c - d \\ b \\ c \\ d \end{bmatrix} : b, c, d \in \mathbb{R} \right\} = \text{Span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

So $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is a basis for V . (If you ignore the first entry, it is easy to

see that these vectors are linearly independent)

(Alternatively: note that, by definition, $V = \text{Nul}([1, 1, 1, 1])$. And for any null space, we know how to find a basis.)

(b) Let

$$A = \begin{bmatrix} -1 & -1 & -1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Then, $V = \text{Col}(A)$ and the orthogonal complement of V is $\text{Nul}(A^T)$. We have:

$$A^T = \begin{bmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 - R1, R3 \rightarrow R3 - R1} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 + R3, R1 \rightarrow R1 + R2} \begin{bmatrix} -1 & 0 & 0 & 1 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 1 \end{bmatrix}$$

Thus,

$$\text{Nul}(A^T) = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} : a = b = c = d \right\} = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

In particular, the dimension of orthogonal complement of V is 1 and $\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ is orthogonal to V .

(This was too much work! (But a good illustration that there is many paths to Rome.) Note again that, by definition, $V = \text{Nul}([1, 1, 1, 1])$. Hence, the orthogonal complement is $\text{Col}([1, 1, 1, 1]^T)$, and we immediately find the vector $[1, 1, 1, 1]^T$ as orthogonal to V .)

(Further note that V is actually defined, right away, as those vectors that are orthogonal to $[1, 1, 1, 1]^T$. Make sure that you can see that by writing out the inner product!)

- (c) No, as we showed in part (b), the dimension of the orthogonal complement of V is 1 so we cannot find two linearly independent vectors in the orthogonal complement of V .

Note: a vector \mathbf{v} is orthogonal to V if and only if \mathbf{v} is in the orthogonal complement of V .

4. Let $A = \begin{bmatrix} 1 & 2 & 1 \\ 4 & 8 & 2 \\ 1 & 2 & 5 \end{bmatrix}$.

- (a) Find an echelon form U of A . What are the column spaces $\text{Col}(A)$, $\text{Col}(U)$? Are they equal?
 (b) Find a basis for $\text{Col}(U)$ and a basis for $\text{Col}(A)$.
 (c) What are the row spaces $\text{Col}(A^T)$, and $\text{Col}(U^T)$. Are they equal?
 (d) Find a basis for the row space of A , $\text{Col}(A^T)$.
 (a) We have:

$$\begin{bmatrix} 1 & 2 & 1 \\ 4 & 8 & 2 \\ 1 & 2 & 5 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 - 4R1, R3 \rightarrow R3 - R1} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & -2 \\ 0 & 0 & 4 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 + 2R2} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

$\text{Col}(A) = \text{Span} \left\{ \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 8 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix} \right\}$ and $\text{Col}(U) = \text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \right\}$. They are not equal since the third entry of any vector in $\text{Col}(U)$ is equal to 0 and in particular, the first column of A is not in $\text{Col}(U)$.

This illustrates the fact that the column space is not preserved by row operations!

- (b) Since the first column and the third column are pivot columns, a basis for $\text{Col}(A)$ is $\left\{ \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix} \right\}$; and a basis for $\text{Col}(U)$ is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \right\}$.
 (c) $\text{Col}(A^T)$ and $\text{Col}(U^T)$ are equal since each row of U is a linear combination of rows of A and vice versa. We have:

$$\text{Col}(A^T) = \text{Col}(U^T) = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix} \right\}$$

The row space, on the other hand, is preserved by row operations!

- (d) Non-zero rows of U form a basis for $\text{Col}(A^T)$. Hence, $\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix} \right\}$ is a basis for $\text{Col}(A^T)$.

5. Let $B = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}$.

- (a) Find a basis for $\text{Nul}(B)$.
 (b) Find two linear independent vectors that are orthogonal to $\text{Nul}(B)$.
 (c) Is there a non-zero vector in \mathbb{R}^2 orthogonal to $\text{Col}(B)$?

Solution: a) We bring B to reduced echelon form:

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R2 \leftrightarrow R1} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \end{bmatrix} \xrightarrow{R2 \leftrightarrow R2 - R1} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}.$$

Hence, vectors in $Nul(B)$ are of the form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Hence, $\left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is a basis of $Nul(B)$.

b) The row space of B is orthogonal to $Nul(B)$. Hence it is enough to find a basis of $Row(B)$.

$$B^T = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 0 \\ 1 & 1 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 - R1, R4 \rightarrow R4 - R1} \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}.$$

Hence, $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is a basis of $Row(B)$ (in this case, we could have argued right away

that the two vectors are independent because it is only two and they are not multiples of each

other). Thus $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is linearly independent and each one is orthogonal to $Nul(B)$.

c) By part a) $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ are the pivot columns of B and hence form a basis of $Col(B)$.

Hence $\dim Col(B) = 2$ and so $\mathbb{R}^2 = Col(B)$. Hence a vector \mathbf{v} that is orthogonal to $Col(B)$, is orthogonal to every vector in \mathbb{R}^2 . In particular, \mathbf{v} is orthogonal to itself. That is $\mathbf{v} \cdot \mathbf{v} = 0$. But then $\mathbf{v} = 0$. Hence, there is no non-zero vector orthogonal to $Col(B)$.

(Another way to see this, is to note that the orthogonal complement has dimension 0, and so only contains the zero vector.)

6. Let $\mathcal{B} := \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$ be a basis of \mathbb{R}^3 . Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation that maps $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ in \mathbb{R}^3 to $\begin{bmatrix} z \\ x \\ y \end{bmatrix}$. Determine the matrix corresponding to T with respect to the bases \mathcal{B} and \mathcal{B} .

Solution: We have:

$$\begin{aligned}
T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) &= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \\
T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) &= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = (-1) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + (-1) \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \\
T\left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\right) &= \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}
\end{aligned}$$

Therefore, the matrix corresponding to T with respect to the bases \mathcal{B} and \mathcal{B} is:

$$A = \begin{bmatrix} 0 & -1 & 0 \\ 1 & -1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

7. Let $I: \mathbb{P}^3 \rightarrow \mathbb{P}^4$ be the linear transformation that maps $p(t)$ to

$$tp(t) + p'(t)$$

Consider the basis $\mathcal{B} = \{1, t, t^2, t^3\}$ of \mathbb{P}^3 and the basis $\mathcal{C} = \{1, t, t^2, t^3, t^4\}$ of \mathbb{P}^4 . Determine the matrix which represents I with respect to the bases \mathcal{B} and \mathcal{C} .

Solution: We have:

$$I(1) = t \cdot 1 - 0 = 0 \cdot 1 + 1 \cdot t + 0 \cdot t^2 + 0 \cdot t^3 + 0 \cdot t^4$$

$$I(t) = t^2 + 1 = 1 \cdot 1 + 0 \cdot t + 1 \cdot t^2 + 0 \cdot t^3 + 0 \cdot t^4$$

$$I(t^2) = t^3 + 2 \cdot t = 0 \cdot 1 + 2 \cdot t + 0 \cdot t^2 + 1 \cdot t^3 + 0 \cdot t^4$$

$$I(t^3) = t^4 + 3 \cdot t^2 = 0 \cdot 1 + 0 \cdot t + 3 \cdot t^2 + 0 \cdot t^3 + 1 \cdot t^4$$

Therefore, the matrix A that represent I with respect to the bases \mathcal{B} and \mathcal{C} is: (we put coefficients of $I(1)$, $I(t)$, $I(t^2)$, and $I(t^3)$ respectively in the first, second, third, and fourth column)

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

8. True or False? Justify your answers.

(a) The map $T: \mathbb{R}^2 \rightarrow \mathbb{R}$ given by $T \begin{bmatrix} a \\ b \end{bmatrix} = \sqrt{a^2 + b^2}$ is a linear transformation.

(b) The map $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $T \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -b \\ a \end{bmatrix}$ is a linear transformation.

(c) If \mathbf{u} and \mathbf{v} in \mathbb{R}^2 are such that $\mathbf{u} \cdot \mathbf{v} = 0$ (\mathbf{u} and \mathbf{v} are orthogonal) then \mathbf{u} and \mathbf{v} are perpendicular (geometrically) to each other.

(d) Let V be a subspace and \mathbf{u}, \mathbf{v} be two vectors in V , then $\mathbf{v} - \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u}$ is orthogonal to \mathbf{u} .

(e) Let $T: V \rightarrow W$ be a linear transformation and $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ be vectors in V . If $T(\mathbf{v}_1), T(\mathbf{v}_2), \dots, T(\mathbf{v}_n)$ are linearly independent then $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are also linearly independent.

(f) Let $T: V \rightarrow W$ be a linear transformation and $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ be vectors in V . If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are linearly independent then $T(\mathbf{v}_1), T(\mathbf{v}_2), \dots, T(\mathbf{v}_n)$ are also linearly independent.

(g) Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be a linear transformation. The dimension of the image of T is equal to 2.

Solution:

(a) False, since we have:

$$T \begin{bmatrix} -1 \\ -1 \end{bmatrix} \neq -T \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

(b) True. Since we have:

$$T \begin{bmatrix} a \\ b \end{bmatrix} + T \begin{bmatrix} a' \\ b' \end{bmatrix} = \begin{bmatrix} -b \\ a \end{bmatrix} + \begin{bmatrix} -b' \\ a' \end{bmatrix} = \begin{bmatrix} -(b+b') \\ a+a' \end{bmatrix} = T \begin{bmatrix} a+a' \\ b+b' \end{bmatrix}, \quad T \begin{bmatrix} ra \\ rb \end{bmatrix} = \begin{bmatrix} -rb \\ ra \end{bmatrix} = r \begin{bmatrix} -b \\ a \end{bmatrix} = rT \begin{bmatrix} a \\ b \end{bmatrix}$$

(Alternatively, can you see which matrix gives rise, by matrix multiplication, to the same map?)

(c) True, let \mathbf{a} and \mathbf{b} be two vectors in \mathbb{R}^2 . Then:

$$[\text{length}(\mathbf{a}-\mathbf{b})]^2 = (\mathbf{a}-\mathbf{b}) \cdot (\mathbf{a}-\mathbf{b}) = \mathbf{a} \cdot \mathbf{a} - 2\mathbf{a} \cdot \mathbf{b} + \mathbf{b} \cdot \mathbf{b} = \mathbf{a} \cdot \mathbf{a} + \mathbf{b} \cdot \mathbf{b} = [\text{length}(\mathbf{a})]^2 + [\text{length}(\mathbf{b})]^2$$

Thus by the Pythagorean theorem, \mathbf{a} and \mathbf{b} are perpendicular to each other.

(d) True, since we have:

$$\mathbf{u} \cdot \left(\mathbf{v} - \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} \right) = \mathbf{u} \cdot \mathbf{v} - \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} \cdot \mathbf{u} = 0$$

(e) True, since if $x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \dots + x_n\mathbf{v}_n = 0$ then $x_1T(\mathbf{v}_1) + x_2T(\mathbf{v}_2) + \dots + x_nT(\mathbf{v}_n) = 0$, but $T(\mathbf{v}_1), T(\mathbf{v}_2), \dots, T(\mathbf{v}_n)$ are linearly independent so all x_i s are equal to 0.

(f) False, consider $T : \mathbb{R}^3 \rightarrow \mathbb{R}$ so that $T(\mathbf{v}) = 0$ (every vector is sent to zero).

(g) False, by (e) we know that the dimension of the image of T is at most 2, but it is not necessarily equal to 2. Consider $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ so that $T(\mathbf{v}) = 0$ (again, every vector is sent to zero).