

Review

- $\{v_1, \dots, v_p\}$ is a **basis** of V if the vectors
 - span V , and
 - are independent.
- The **dimension** of V is the number of elements in a basis.
- The columns of A are linearly independent
 - \iff each column of A contains a pivot.

Warmup

Example 1. Find a basis and the dimension of

$$W = \left\{ \left[\begin{array}{c} a+b+2c \\ 2a+2b+4c+d \\ b+c+d \\ 3a+3c+d \end{array} \right] : a, b, c, d \text{ real} \right\}.$$

Solution.

First, note that

$$W = \text{span} \left\{ \left[\begin{array}{c} 1 \\ 2 \\ 0 \\ 3 \end{array} \right], \left[\begin{array}{c} 1 \\ 2 \\ 1 \\ 0 \end{array} \right], \left[\begin{array}{c} 2 \\ 4 \\ 1 \\ 3 \end{array} \right], \left[\begin{array}{c} 0 \\ 1 \\ 1 \\ 1 \end{array} \right] \right\}.$$

Is $\dim W = 4$? No, because the third vector is the sum of the first two.

Suppose we did not notice...

$$\begin{aligned} A = \begin{bmatrix} 1 & 1 & 2 & 0 \\ 2 & 2 & 4 & 1 \\ 0 & 1 & 1 & 1 \\ 3 & 0 & 3 & 1 \end{bmatrix} &\rightsquigarrow \begin{bmatrix} 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & -3 & -3 & 1 \end{bmatrix} \\ &\rightsquigarrow \begin{bmatrix} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & -3 & -3 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\ &\rightsquigarrow \begin{bmatrix} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

Not a pivot in every column, hence the 4 vectors are dependent.

[Not necessary here, but:

To get a relation, solve $A\mathbf{x} = \mathbf{0}$. Set free variable $x_3 = 1$.

Then $x_4 = 0$, $x_2 = -x_3 = -1$ and $x_1 = -x_2 - 2x_3 = -1$. The relation is

$$-\begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 2 \\ 4 \\ 1 \\ 3 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \mathbf{0}.$$

Precisely, what we “noticed” to begin with.]

Hence, a basis for W is $\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$ and $\dim W = 3$.

It follows from the echelon form that these vectors are independent.

Every set of linearly independent vectors can be extended to a basis.

In other words, let $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ be linearly independent vectors in V . If V has dimension d , then we can find vectors $\mathbf{v}_{p+1}, \dots, \mathbf{v}_d$ such that $\{\mathbf{v}_1, \dots, \mathbf{v}_d\}$ is a basis of V .

Example 2. Consider

$$H = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

- Give a basis for H . What is the dimension of H ?
- Extend the basis of H to a basis of \mathbb{R}^3 .

Solution.

- The vectors are independent. By definition, they span H .

Therefore, $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$ is a basis for H .

In particular, $\dim H = 2$.

- $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$ is not a basis for \mathbb{R}^3 . Why?

Because a basis for \mathbb{R}^3 needs to contain 3 vectors.

Or, because, for instance, $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ is not in H .

So: just add this (or any other) missing vector!

By construction, $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is independent.

Hence, this automatically is a basis of \mathbb{R}^3 .

Bases for column and null spaces

Bases for null spaces

To find a basis for $\text{Nul}(A)$:

- find the parametric form of the solutions to $A\mathbf{x} = \mathbf{0}$,
- express solutions \mathbf{x} as a linear combination of vectors with the free variables as coefficients;
- these vectors form a basis of $\text{Nul}(A)$.

Example 3. Find a basis for $\text{Nul}(A)$ with

$$A = \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 6 & 12 & 15 & 0 & 3 \end{bmatrix}.$$

Solution.

$$\begin{aligned} \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 6 & 12 & 15 & 0 & 3 \end{bmatrix} &\rightsquigarrow \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 0 & 0 & 3 & -6 & -15 \end{bmatrix} \\ &\rightsquigarrow \begin{bmatrix} 1 & 2 & 2 & 1 & 3 \\ 0 & 0 & 1 & -2 & -5 \end{bmatrix} \\ &\rightsquigarrow \begin{bmatrix} 1 & 2 & 0 & 5 & 13 \\ 0 & 0 & 1 & -2 & -5 \end{bmatrix} \end{aligned}$$

The solutions to $A\mathbf{x} = \mathbf{0}$ are:

$$\mathbf{x} = \begin{bmatrix} -2x_2 - 5x_4 - 13x_5 \\ x_2 \\ 2x_4 + 5x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -5 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -13 \\ 0 \\ 5 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Hence, } \text{Nul}(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -13 \\ 0 \\ 5 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

These vectors are clearly independent.

If you don't see it, do compute an echelon form!

(permute first and third row to the bottom)

Better yet: note that the first vector corresponds to the solution with $x_2 = 1$ and the other free variables $x_4 = 0$, $x_5 = 0$. The second vector corresponds to the solution with $x_4 = 1$ and the other free variables $x_2 = 0$, $x_5 = 0$. The third vector ...

$$\text{Hence, } \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -13 \\ 0 \\ 5 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis for } \text{Nul}(A).$$

Bases for column spaces

Recall that the columns of A are independent

$\iff Ax = \mathbf{0}$ has only the trivial solution (namely, $x = \mathbf{0}$),

$\iff A$ has no free variables.

A basis for $\text{Col}(A)$ is given by the pivot columns of A .

Example 4. Find a basis for $\text{Col}(A)$ with

$$A = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix}.$$

Solution.

$$\begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & -1 & -5 \\ 0 & 0 & 2 & 10 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\ \rightsquigarrow \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & -1 & -5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The pivot columns are the first and third.

Hence, a basis for $\text{Col}(A)$ is $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 2 \\ 0 \end{bmatrix} \right\}$.

Warning: For the basis of $\text{Col}(A)$, you have to take the columns of A , not the columns of an echelon form.

Row operations do not preserve the column space.

[For instance, $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \xrightarrow{R1 \leftrightarrow R2} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ have different column spaces (of the same dimension).]