

Example 132. Consider the following system of (second-order) initial value problems:

$$\begin{aligned} y_1'' &= 2y_1' - 3y_2' + 7y_2 & y_1(0) &= 2, \quad y_1'(0) = 3, \quad y_2(0) = -1, \quad y_2'(0) = 1 \\ y_2'' &= 4y_1' + y_2' - 5y_1 \end{aligned}$$

Write it as a first-order initial value problem in the form $\mathbf{y}' = A\mathbf{y}$, $\mathbf{y}(0) = \mathbf{y}_0$.

Solution. Introduce $y_3 = y_1'$ and $y_4 = y_2'$. Then, the given system translates into

$$\mathbf{y}' = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 7 & 2 & -3 \\ -5 & 0 & 4 & 1 \end{bmatrix} \mathbf{y}, \quad \mathbf{y}(0) = \begin{bmatrix} 2 \\ -1 \\ 3 \\ 1 \end{bmatrix}.$$

The Jordan normal form

Note that we currently only know how to compute e^{At} when A is diagonalizable. Our next goal is to be able to compute the matrix exponential for all matrices.

Example 133. Diagonalize, if possible, the matrix $A = \begin{bmatrix} 4 & 1 \\ & 4 \end{bmatrix}$.

Solution. The eigenvalues of A are 4, 4.
 However, the 4-eigenspace $\text{null}\left(\begin{bmatrix} 0 & 1 \\ & 0 \end{bmatrix}\right)$ is only 1-dimensional.
 Hence, A is not diagonalizable.

Definition 134. A λ -Jordan block is a matrix of the form $\begin{bmatrix} \lambda & 1 & & \\ & \lambda & \ddots & \\ & & \ddots & 1 \\ & & & \lambda \end{bmatrix}$.

Note that if this matrix is $m \times m$, then its only eigenvalue is λ (repeated m times).
 As in the previous example, the λ -eigenspace is 1-dimensional (which is as small as possible).

Theorem 135. (Jordan normal form) Every $n \times n$ matrix A can be written as $A = PJP^{-1}$, where J is a block diagonal matrix

$$J = \begin{bmatrix} J_1 & & & \\ & J_2 & & \\ & & \ddots & \\ & & & J_r \end{bmatrix}$$

with each J_i a Jordan block. J is called the **Jordan normal form** of A .
 Up to the ordering of the Jordan blocks, the Jordan normal form of A is unique.

Comment. If A is diagonalizable, then J is just a usual diagonal matrix.

Example 136. What are the possible Jordan normal forms of a 3×3 matrix with eigenvalues 4, 4, 4?

Solution. $\begin{bmatrix} 4 & & \\ & 4 & \\ & & 4 \end{bmatrix}, \begin{bmatrix} 4 & & \\ & 4 & 1 \\ & & 4 \end{bmatrix}, \begin{bmatrix} 4 & 1 & \\ & 4 & 1 \\ & & 4 \end{bmatrix}$

The dimension of the 4-eigenspace equals the number of Jordan blocks: 3, 2, 1, respectively.

Comment. Note that, say, $\begin{bmatrix} 4 & 1 \\ & 4 \\ & & 4 \end{bmatrix}$ is equivalent to $\begin{bmatrix} 4 & & \\ & 4 & 1 \\ & & 4 \end{bmatrix}$ because the ordering of the diagonal blocks does not matter (as you know from diagonalization).

Example 137.

- (a) What are the possible Jordan normal forms of a 3×3 matrix with eigenvalues 3, 3, 3?
- (b) What are the possible Jordan normal forms of a 4×4 matrix with eigenvalues 3, 3, 3, 3?
- (c) What if the matrix is 5×5 and has eigenvalues 4, 4, 3, 3, 3?

Solution.

(a) $\begin{bmatrix} 3 & & \\ & 3 & \\ & & 3 \end{bmatrix}, \begin{bmatrix} 3 & & \\ & 3 & 1 \\ & & 3 \end{bmatrix}, \begin{bmatrix} 3 & 1 & \\ & 3 & 1 \\ & & 3 \end{bmatrix}$

The dimension of the 3-eigenspace equals the number of Jordan blocks: 3, 2, 1, respectively.

Comment. Note that, say, $\begin{bmatrix} 3 & 1 \\ & 3 \\ & & 3 \end{bmatrix}$ is equivalent to $\begin{bmatrix} 3 & & \\ & 3 & 1 \\ & & 3 \end{bmatrix}$ because the ordering of the diagonal blocks does not matter (as you know from diagonalization).

(b) Now, there are 5 possibilities:

$\begin{bmatrix} 3 & & & \\ & 3 & & \\ & & 3 & \\ & & & 3 \end{bmatrix}, \begin{bmatrix} 3 & & & \\ & 3 & & \\ & & 3 & 1 \\ & & & 3 \end{bmatrix}, \begin{bmatrix} 3 & 1 & & \\ & 3 & & \\ & & 3 & 1 \\ & & & 3 \end{bmatrix}, \begin{bmatrix} 3 & & & \\ & 3 & 1 & \\ & & 3 & 1 \\ & & & 3 \end{bmatrix}, \begin{bmatrix} 3 & 1 & & \\ & 3 & 1 & \\ & & 3 & 1 \\ & & & 3 \end{bmatrix}$

The dimension of the 3-eigenspace equals the number of Jordan blocks: 4, 3, 2, 2, 1, respectively.

(c) $\begin{bmatrix} 3 & & & & \\ & 3 & & & \\ & & 3 & & \\ & & & 4 & \\ & & & & 4 \end{bmatrix}, \begin{bmatrix} 3 & & & & \\ & 3 & & & \\ & & 3 & & \\ & & & 4 & 1 \\ & & & & 4 \end{bmatrix}, \begin{bmatrix} 3 & & & & \\ & 3 & 1 & & \\ & & 3 & & \\ & & & 4 & \\ & & & & 4 \end{bmatrix}, \begin{bmatrix} 3 & & & & \\ & 3 & 1 & & \\ & & 3 & & \\ & & & 4 & 1 \\ & & & & 4 \end{bmatrix}, \begin{bmatrix} 3 & 1 & & & \\ & 3 & 1 & & \\ & & 3 & & \\ & & & 4 & \\ & & & & 4 \end{bmatrix}, \begin{bmatrix} 3 & 1 & & & \\ & 3 & 1 & & \\ & & 3 & & \\ & & & 4 & 1 \\ & & & & 4 \end{bmatrix}$

Note that this is just all possible (namely, 3) Jordan normal forms of a 3×3 matrix with eigenvalues 3, 3, 3 combined with all possible (namely, 2) Jordan normal forms of a 2×2 matrix with eigenvalues 4, 4. In total, that makes $3 \cdot 2 = 6$ possibilities.

Comment. Let $p(n)$ be the number of inequivalent Jordan normal forms of an $n \times n$ matrix with a single eigenvalue, n times repeated. We have seen that $p(2) = 2$, $p(3) = 3$, $p(4) = 5$. Note that $p(n)$ is equal to the number of ways of writing n as an ordered sum of positive integers: for instance, $p(4) = 5$ because $4 = 3 + 1 = 2 + 2 = 2 + 1 + 1 = 1 + 1 + 1 + 1$.

$p(n)$ is referred to as the **partition function** and, surprisingly, is a remarkably interesting mathematical object.

[https://en.wikipedia.org/wiki/Partition_function_\(number_theory\)](https://en.wikipedia.org/wiki/Partition_function_(number_theory))

