

Review. If $\mathbf{v}_1, \dots, \mathbf{v}_n$ are orthogonal, the orthogonal projection of \mathbf{w} onto $\text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ is

$$\hat{\mathbf{w}} = \frac{\mathbf{w} \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 + \dots + \frac{\mathbf{w} \cdot \mathbf{v}_n}{\mathbf{v}_n \cdot \mathbf{v}_n} \mathbf{v}_n.$$

Example 59. Determine the projection of $\begin{bmatrix} 3 \\ 7 \\ 4 \end{bmatrix}$ onto $W = \text{span}\left\{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right\}$.

Comment. We know how to do this using least squares.

However, realizing that $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ are orthogonal makes things even easier.

Solution. (using orthogonality) As in Example 58, the projection of $\begin{bmatrix} 3 \\ 7 \\ 4 \end{bmatrix}$ onto $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$ is $-2\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$ and the projection of $\begin{bmatrix} 3 \\ 7 \\ 4 \end{bmatrix}$ onto $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ is $4\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

Hence, the orthogonal projection of $\begin{bmatrix} 3 \\ 7 \\ 4 \end{bmatrix}$ onto $W = \text{span}\left\{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right\}$ is $-2\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + 4\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \\ 4 \end{bmatrix}$.

Important note. Note that, at this point, we can easily extend $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ to an orthogonal basis of \mathbb{R}^3 :

That is because the error $\begin{bmatrix} 3 \\ 7 \\ 4 \end{bmatrix} - \begin{bmatrix} -2 \\ 2 \\ 4 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 0 \end{bmatrix}$ is orthogonal to both of the existing basis vectors.

Therefore $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 5 \\ 0 \end{bmatrix}$ is an orthogonal basis of \mathbb{R}^3 .

Gram–Schmidt

This idea (see “important note” above) for creating orthogonal vectors underlies Gram–Schmidt:

(Gram–Schmidt orthogonalization)

Given a basis $\mathbf{w}_1, \mathbf{w}_2, \dots$ for W , produce an orthogonal basis $\mathbf{q}_1, \mathbf{q}_2, \dots$ for W .

- $\mathbf{q}_1 = \mathbf{w}_1$
- $\mathbf{q}_2 = \mathbf{w}_2 - \left(\text{projection of } \mathbf{w}_2 \text{ onto } \mathbf{q}_1\right)$
- $\mathbf{q}_3 = \mathbf{w}_3 - \left(\text{projection of } \mathbf{w}_3 \text{ onto } \mathbf{q}_1\right) - \left(\text{projection of } \mathbf{w}_3 \text{ onto } \mathbf{q}_2\right)$
- $\mathbf{q}_4 = \dots$

Comment. Since $\mathbf{q}_1, \mathbf{q}_2$ are orthogonal, $\left(\text{projection of } \mathbf{w}_3 \text{ onto } \text{span}\{\mathbf{q}_1, \mathbf{q}_2\}\right) = \left(\text{projection of } \mathbf{w}_3 \text{ onto } \mathbf{q}_1\right) + \left(\text{projection of } \mathbf{w}_3 \text{ onto } \mathbf{q}_2\right)$.

Important comment. When working numerically it actually saves time to compute an orthonormal basis $\mathbf{q}_1, \mathbf{q}_2, \dots$ by the same approach but always normalizing each \mathbf{q}_i along the way. The reason this saves time is that now the projections onto \mathbf{q}_i only require a single dot product (instead of two). This is called **Gram–Schmidt orthonormalization**.

Note. When normalizing, the orthonormal basis $\mathbf{q}_1, \mathbf{q}_2, \dots$ is the unique one with the property that $\text{span}\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_k\} = \text{span}\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k\}$ for all $k = 1, 2, \dots$

Example 60. Find an orthogonal basis for $W = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right\}$.

Solution. We already have the basis $w_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $w_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ for W . However, that basis is not orthogonal.

We can construct an orthogonal basis q_1, q_2 for W as follows:

- $q_1 = w_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Since this is our first basis vector, we don't yet have other basis vectors it needs to be orthogonal to.

- $q_2 = w_2 - \left(\begin{array}{c} \text{projection of} \\ w_2 \text{ onto } q_1 \end{array}\right) = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/3 \\ -4/3 \\ 2/3 \end{bmatrix}$

Make sure our way to construct q_2 makes sense to you!

q_2 is the error of the projection of w_2 onto q_1 . This guarantees that it is orthogonal to q_1 .

On the other hand, since q_2 is a combination of w_2 and q_1 , we know that q_2 actually is in W .

We have thus found the orthogonal basis $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2/3 \\ -4/3 \\ 2/3 \end{bmatrix}$ for W .

Important comment. Normalizing these, we get $\frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$, which is an orthonormal basis for W .

Comment. There are, of course, many orthogonal bases q_1, q_2 for W . Up to the length of the vectors, ours is the unique one with the property that $\text{span}\{q_1\} = \text{span}\{w_1\}$ and $\text{span}\{q_1, q_2\} = \text{span}\{w_1, w_2\}$.