

Example 155. What are the possible Jordan normal forms of a 6×6 matrix with eigenvalues $3, 3, 7, 7, 7, 7$?

Solution. There are $2 \cdot 5 = 10$ possible Jordan normal forms for such a matrix:

$$\begin{matrix} \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, \\ \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix}, & \begin{bmatrix} 3 & & & & & \\ & 3 & & & & \\ & & 7 & & & \\ & & & 7 & & \\ & & & & 7 & \\ & & & & & 7 \end{bmatrix} \end{matrix}$$

Example 156. How many different Jordan normal forms are there in the following cases?

- (a) A 8×8 matrix with eigenvalues $1, 1, 2, 2, 2, 4, 4, 4$?
- (b) A 11×11 matrix with eigenvalues $1, 1, 1, 2, 2, 2, 2, 4, 4, 4, 4$?

Solution.

- (a) $2 \cdot 3 \cdot 3 = 18$ possible Jordan normal forms
- (b) $3 \cdot 5 \cdot 5 = 75$ possible Jordan normal forms

Review.

- Let A be $n \times n$. The matrix exponential is

$$e^A = I + A + \frac{1}{2!}A^2 + \frac{1}{3!}A^3 + \dots$$

Then, $\frac{d}{dt}e^{At} = Ae^{At}$.

Why? $\frac{d}{dt}e^{At} = \frac{d}{dt}\left(I + At + \frac{1}{2!}A^2t^2 + \frac{1}{3!}A^3t^3 + \dots\right) = A + \frac{1}{1!}A^2t + \frac{1}{2!}A^3t^2 + \dots = Ae^{At}$

- If $A = PDP^{-1}$, then $e^A = Pe^DP^{-1}$.
- The solution to $\mathbf{y}' = A\mathbf{y}$, $\mathbf{y}(0) = \mathbf{y}_0$ is $\mathbf{y}(t) = e^{At}\mathbf{y}_0$.
Why? Because $\mathbf{y}'(t) = Ae^{At}\mathbf{y}_0 = A\mathbf{y}(t)$ and $\mathbf{y}(0) = e^{0A}\mathbf{y}_0 = \mathbf{y}_0$.

Example 157. The matrix exponential shares many other properties of the usual exponential:

- $e^Ae^B = e^{A+B} = e^Be^A$ if $AB = BA$

Why the condition $AB = BA$? By the Taylor series, $e^{A+B} = I + (A+B) + \frac{(A+B)^2}{2!} + \dots$. In order to simplify that to

$$e^Ae^B = \left(I + A + \frac{A^2}{2!} + \dots\right)\left(I + B + \frac{B^2}{2!} + \dots\right),$$

we need that $(A+B)^2 = A^2 + AB + BA + B^2$ is the same as $A^2 + 2AB + B^2$. That's only the case if $AB = BA$.

- e^A is invertible and $(e^A)^{-1} = e^{-A}$
Why? That actually follows from the previous property.

Example 158. Solve the differential equation

$$\mathbf{y}' = \begin{bmatrix} 2 & 1 \\ & 2 \end{bmatrix} \mathbf{y}, \quad \mathbf{y}(0) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}.$$

Solution.

- If $A = \begin{bmatrix} 2 & 1 \\ & 2 \end{bmatrix}$, then the solution is $\mathbf{y}(t) = e^{At} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$.

The only difficulty is in computing e^{At} since we already observed that A is not diagonalizable.

- Write $A = \begin{bmatrix} 2 & 1 \\ & 2 \end{bmatrix} = 2I + N$ with $N = \begin{bmatrix} 0 & 1 \\ & 0 \end{bmatrix}$. Note that $2I$ and N commute.

Hence, $e^{At} = e^{2It+Nt} = e^{2It}e^{Nt}$.

- Note that $N^2 = \begin{bmatrix} 0 & 0 \\ & 0 \end{bmatrix}$. Hence, $e^{Nt} = I + Nt + \frac{t^2}{2!}N^2 + \dots = I + Nt = \begin{bmatrix} 1 & t \\ & 1 \end{bmatrix}$.

- Combined, $e^{At} = e^{2It+Nt} = e^{2It}e^{Nt} = \begin{bmatrix} e^{2t} & \\ & e^{2t} \end{bmatrix} \begin{bmatrix} 1 & t \\ & 1 \end{bmatrix} = \begin{bmatrix} e^{2t} & te^{2t} \\ & e^{2t} \end{bmatrix}$.

In particular, $\mathbf{y}(t) = e^{At} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} (t-1)e^{2t} \\ e^{2t} \end{bmatrix} = \begin{bmatrix} t-1 \\ 1 \end{bmatrix} e^{2t}$.

Check. We should verify that $y_1 = (t-1)e^{2t}$ and $y_2 = e^{2t}$ satisfy $y_1' = 2y_1 + y_2$ and $y_2' = 2y_2$.

Indeed, $y_1' = e^{2t} + (t-1)2e^{2t}$ equals $2y_1 + y_2 = 2(t-1)e^{2t} + e^{2t}$.

Comment. For applications, having solutions like $te^{\lambda t}$ or $t \cos(\lambda t)$ (when the eigenvalues are imaginary) is connected to the phenomenon of **resonance**, which you may have already seen.