

**Example 21.** Consider the following linear system:

$$\begin{aligned} x_1 + 6x_2 + x_4 &= 0 \\ 2x_1 + 12x_2 + x_3 - 2x_4 &= 5 \\ x_1 + 6x_2 - x_3 + 11x_4 + x_5 &= 2 \end{aligned}$$

Gaussian elimination:

$$\begin{aligned} &\left[ \begin{array}{ccccc|c} 1 & 6 & 0 & 1 & 0 & 0 \\ 2 & 12 & 1 & -2 & 0 & 5 \\ 1 & 6 & -1 & 11 & 1 & 2 \end{array} \right] \xrightarrow{\substack{R_2 - 2R_1 \Rightarrow R_2 \\ R_3 - R_1 \Rightarrow R_3}} \left[ \begin{array}{ccccc|c} 1 & 6 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -4 & 0 & 5 \\ 0 & 0 & -1 & 10 & 1 & 2 \end{array} \right] \xrightarrow{R_3 + R_2 \Rightarrow R_3} \left[ \begin{array}{ccccc|c} 1 & 6 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -4 & 0 & 5 \\ 0 & 0 & 0 & 6 & 1 & 7 \end{array} \right] \\ &\xrightarrow{\frac{1}{6}R_3 \Rightarrow R_3} \left[ \begin{array}{ccccc|c} 1 & 6 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -4 & 0 & 5 \\ 0 & 0 & 0 & 1 & \frac{1}{6} & \frac{7}{6} \end{array} \right] \xrightarrow{\substack{R_1 - R_3 \Rightarrow R_1 \\ R_2 + 4R_3 \Rightarrow R_2}} \left[ \begin{array}{ccccc|c} 1 & 6 & 0 & 0 & -\frac{1}{6} & -\frac{7}{6} \\ 0 & 0 & 1 & 0 & \frac{2}{3} & \frac{29}{3} \\ 0 & 0 & 0 & 1 & \frac{1}{6} & \frac{7}{6} \end{array} \right] \end{aligned}$$

- The system is consistent.
 

**Why?** We were able to see that at the moment we had an echelon form. The echelon form had no row of the type  $[0 \ 0 \ \dots \ 0 \ | \ b]$  with  $b \neq 0$ , and so the system is consistent.
- The pivots are located in columns 1, 3, 4.
- Correspondingly, our free variables are  $x_2, x_5$ .  
We set  $x_2 = s_1$  and  $x_5 = s_2$ , where  $s_1, s_2$  can be any numbers (free parameters).
- Solving each equation for the pivot variable, we find that the general solution is:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -\frac{7}{6} - 6s_1 + \frac{1}{6}s_2 \\ s_1 \\ \frac{29}{3} - \frac{2}{3}s_2 \\ \frac{7}{6} - \frac{1}{6}s_2 \\ s_2 \end{bmatrix}$$

## 5 Vectors and linear combinations

**Example 22.** We have already encountered **matrices** such as

$$\begin{bmatrix} 1 & 4 & 2 & 3 \\ 2 & -1 & 2 & 2 \\ 3 & 2 & -2 & 0 \end{bmatrix}.$$

Each column is what we call a **(column) vector**.

In this example, each column vector has 3 entries and so lies in  $\mathbb{R}^3$ .

**Example 23.** A fundamental property of vectors is that vectors of the same kind can be **added** and **scaled**.

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \\ 5 \end{bmatrix}, \quad 7 \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 7x_1 \\ 7x_2 \\ 7x_3 \end{bmatrix}.$$

**Example 24.** Let us return to the system we solved at the beginning of this class. Note that we already wrote its general solution as a vector (in  $\mathbb{R}^5$ ). Further note that we can also write it as

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -\frac{7}{6} - 6s_1 + \frac{1}{6}s_2 \\ s_1 \\ \frac{29}{3} - \frac{2}{3}s_2 \\ \frac{7}{6} - \frac{1}{6}s_2 \\ s_2 \end{bmatrix} = \begin{bmatrix} -\frac{7}{6} \\ 0 \\ \frac{29}{3} \\ \frac{7}{6} \\ 0 \end{bmatrix} + s_1 \begin{bmatrix} -6 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s_2 \begin{bmatrix} \frac{1}{6} \\ 0 \\ -\frac{2}{3} \\ -\frac{1}{6} \\ 1 \end{bmatrix}.$$

**Comment.** The first vector on the right-hand side is a **particular solution** to our linear system (because that's the solution we get when choosing  $s_1 = 0$  and  $s_2 = 0$ ). Plug the other two vectors into our linear system and observe that they solve the equations if the right-hand sides are replaced with 0 (we will call this the **homogeneous system** corresponding to our linear system).

Adding and scaling vectors, the most general thing we can do is:

**Definition 25.** Given vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$  in  $\mathbb{R}^n$  and scalars  $c_1, c_2, \dots, c_m$ , the vector

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_m\mathbf{v}_m$$

is a **linear combination** of  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ .

The scalars  $c_1, \dots, c_m$  are the **coefficients** or **weights**.

**Example 26.** Express  $\begin{bmatrix} 3 \\ -1 \end{bmatrix}$  as a linear combination of  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

**Solution.** Clearly,  $\begin{bmatrix} 3 \\ -1 \end{bmatrix} = 3\begin{bmatrix} 1 \\ 0 \end{bmatrix} - 1\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

**Example 27.** Express  $\begin{bmatrix} 3 \\ -1 \end{bmatrix}$  as a linear combination of  $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$  and  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

**Solution.** We have to find  $c_1$  and  $c_2$  such that

$$c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}.$$

This is the same as:

$$\begin{aligned} c_1 + 2c_2 &= 3 \\ 3c_1 + c_2 &= -1 \end{aligned}$$

Solving, we find  $c_1 = -1$  and  $c_2 = 2$ .

Indeed,

$$-\begin{bmatrix} 1 \\ 3 \end{bmatrix} + 2\begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}.$$