

1 Introduction to systems of linear equations

Definition 1. A **linear equation** in the variables x_1, \dots, x_n is an equation that can be written as

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

for some numbers b, a_1, a_2, \dots, a_n .

Example 2. Which of the following equations are linear?

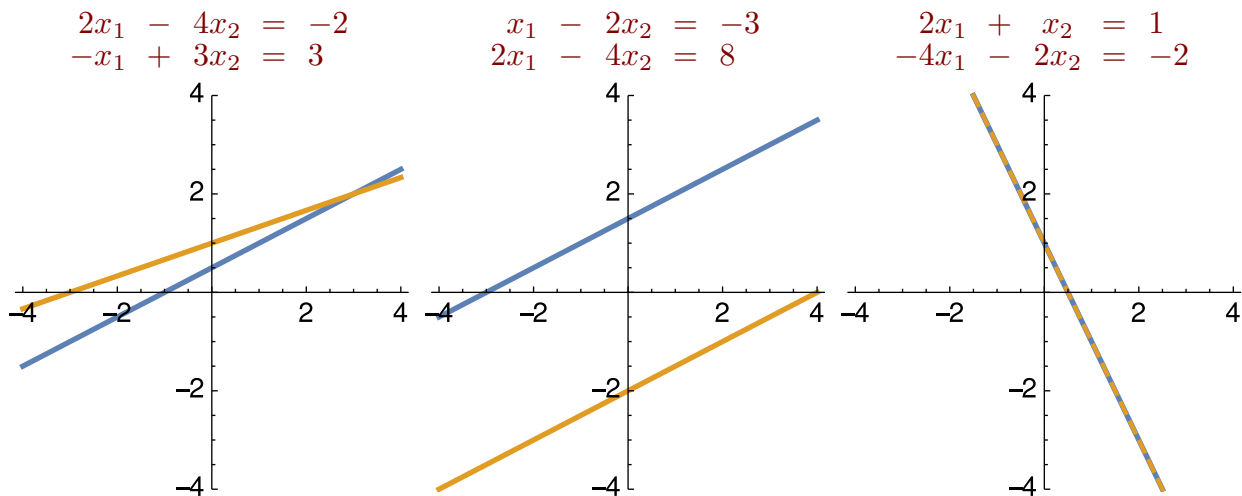
- $4x_1 - 5x_2 + 2 = x_1$ linear: $3x_1 - 5x_2 = -2$
- $4x_1 - 6x_2 = x_1x_2$ not linear: x_1x_2
- $x_2 = 2\sqrt{x_1} - 7$ not linear: $\sqrt{x_1}$
- $x_2 = 2(\sqrt{6} - x_1) + x_3$ linear: $2x_1 + x_2 - x_3 = 2\sqrt{6}$

Definition 3. A **system of linear equations** (or a **linear system**) is a collection of one or more linear equations involving the same set of variables, say, x_1, x_2, \dots, x_n .

A **solution** of a linear system is a list (s_1, s_2, \dots, s_n) of numbers that makes each equation in the system true when the values s_1, s_2, \dots, s_n are substituted for x_1, x_2, \dots, x_n , respectively.

Example 4. (Two equations in two variables)

In each case, sketch the set of all solutions.



Theorem 5. A linear system has either

- no solution, or
- one unique solution, or
- infinitely many solutions.

Definition 6. A system is **consistent** if a solution exists.

2 How to solve systems of linear equations

Strategy: replace system with an equivalent system which is easier to solve

Example 7. Let us solve the systems from the previous example:

$$\begin{array}{l} \bullet \quad \begin{array}{l} 2x_1 - 4x_2 = -2 \\ -x_1 + 3x_2 = 3 \end{array} \quad \begin{array}{l} R_2 + \frac{1}{2}R_1 \Rightarrow R_2 \\ \hline \end{array} \quad \begin{array}{l} 2x_1 - 4x_2 = -2 \\ x_2 = 2 \end{array} \end{array}$$

Once in this **triangular** form, we find the solutions by **back-substitution**:

$$x_2 = 2, \quad x_1 = 3$$

$$\bullet \quad \begin{array}{l} x_1 - 2x_2 = -3 \\ 2x_1 - 4x_2 = 8 \end{array} \quad \begin{array}{l} R_2 - 2R_1 \Rightarrow R_2 \\ \hline \end{array} \quad \begin{array}{l} x_1 - 2x_2 = -3 \\ 0 = 14 \end{array}$$

Since $0 \neq 14$, this system is inconsistent. It has no solutions.

$$\bullet \quad \begin{array}{l} 2x_1 + x_2 = 1 \\ -4x_1 - 2x_2 = -2 \end{array} \quad \begin{array}{l} R_2 + 2R_1 \Rightarrow R_2 \\ \hline \end{array} \quad \begin{array}{l} 2x_1 + x_2 = 1 \\ 0 = 0 \end{array}$$

In this case, the second equation was redundant (it clearly is a multiple of the first one). To write down solutions to the system, we set $x_2 = s$, where s is a **free parameter** (i.e. it can take any value). Then, we again proceed by back-substitution:

$$x_2 = s, \quad x_1 = \frac{1-s}{2}$$

Example 8. The same approach works for more complicated systems.

$$\begin{array}{l} x_1 - 2x_2 + x_3 = 0 \\ 2x_1 - 2x_2 - 6x_3 = 8 \\ -4x_1 + 5x_2 + 9x_3 = -9 \end{array} \quad \begin{array}{l} \\ \downarrow R_2 - 2R_1 \Rightarrow R_2 \\ \downarrow R_3 + 4R_1 \Rightarrow R_3 \end{array}$$

$$\begin{array}{l} x_1 - 2x_2 + x_3 = 0 \\ 2x_2 - 8x_3 = 8 \\ -3x_2 + 13x_3 = -9 \end{array} \quad \begin{array}{l} \\ \\ \downarrow R_3 + \frac{3}{2}R_2 \Rightarrow R_3 \end{array}$$

$$\begin{array}{l} x_1 - 2x_2 + x_3 = 0 \\ 2x_2 - 8x_3 = 8 \\ x_3 = 3 \end{array}$$

By back-substitution:

$$x_3 = 3, \quad x_2 = 16, \quad x_1 = 29.$$

Note. It is always a good idea to check our answer. Let us check that $(29, 16, 3)$ indeed solves the original system:

$$\begin{array}{l} x_1 - 2x_2 + x_3 = 0 \\ 2x_1 - 2x_2 - 6x_3 = 8 \\ -4x_1 + 5x_2 + 9x_3 = -9 \end{array} \quad \begin{array}{l} 29 - 2 \cdot 16 + 3 \stackrel{\checkmark}{=} 0 \\ 2 \cdot 29 - 2 \cdot 16 - 6 \cdot 3 \stackrel{\checkmark}{=} 8 \\ -4 \cdot 29 + 5 \cdot 16 + 9 \cdot 3 \stackrel{\checkmark}{=} -9 \end{array}$$

Example 9. (Exercise!) Solve the following linear system:

$$\begin{array}{l} x_1 + 2x_2 - x_3 = 1 \\ -x_1 - x_2 + 2x_3 = 1 \\ 2x_1 + 4x_2 + x_3 = 5 \end{array}$$

(To stick to our strategy, your first step should be $R_2 + R_1 \Rightarrow R_2$, $R_3 - 2R_1 \Rightarrow R_3$.)