Sketch of Lecture 15

Review. spaces, basis, dimension, col(A), row(A), null(A)

Example 104.

(a) Consider $V = \operatorname{col}\left(\begin{bmatrix} 1 & 3\\ 2 & 4 \end{bmatrix}\right)$. By definition, $V = \operatorname{span}\left\{\begin{bmatrix} 1\\ 2 \end{bmatrix}, \begin{bmatrix} 3\\ 4 \end{bmatrix}\right\}$. Since the vectors $\begin{bmatrix} 1\\ 2 \end{bmatrix}, \begin{bmatrix} 3\\ 4 \end{bmatrix}$ are linearly independent (it is only two, and they are clearly not multiples of each other), these two vectors are a basis for V. In particular, the dimension of V is 2. It automatically follows from that (see the next theorem) that $V = \mathbb{R}^2$.

(b) Consider
$$W = \operatorname{row}\left(\begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}\right)$$
. By definition, $W = \operatorname{span}\left\{\begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}\right\}$

Note that $W = \operatorname{col}\left(\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}\right)$ and, in general, $\operatorname{row}(A) = \operatorname{col}(A^T)$.

[This means that every statement about column spaces translate into an equivalent statement for row spaces, and vice versa.]

Since the vectors $\begin{bmatrix} 1\\ 3 \end{bmatrix}, \begin{bmatrix} 2\\ 4 \end{bmatrix}$ are linearly independent, and so are a basis for V.

Theorem 105. Let V be a vector space of dimension d.

- If the *d* vectors $v_1, v_2, ..., v_d$ from *V* are independent, then they are a basis of *V*.
- If the d vectors $v_1, v_2, ..., v_d$ span V, then they are a basis of V.

In particular, it follows from the first part that we can easily decide whether a bunch of vectors is a basis of \mathbb{R}^n : they are a basis if and only if these are exactly n vectors and they are independent.

Example 106. Which of the following sets are a basis for \mathbb{R}^2 ?

 $(\mathsf{a})\left[\begin{array}{c}1\\1\end{array}\right]$

Any basis of \mathbb{R}^2 has to have two vectors. So a single vector cannot constitute a basis for \mathbb{R}^2 . [Note this set of one vector is linearly independent (why?!) but $\operatorname{span}\left\{ \begin{bmatrix} 1\\1 \end{bmatrix} \neq \mathbb{R}^2 \right\}$.

 $(\mathsf{b})\left[\begin{array}{c}1\\0\end{array}\right],\left[\begin{array}{c}0\\1\end{array}\right]$

These are two vectors, and they are clearly independent. Hence, they are a basis of \mathbb{R}^2 . Recall that this special basis is called the standard basis.

 $(\mathsf{c})\left[\begin{array}{c}2\\1\end{array}\right],\left[\begin{array}{c}4\\2\end{array}\right]$

These are two vectors, and they are clearly independent. Hence, they are a basis of \mathbb{R}^2 . Recall that this special basis is called the standard basis.

 $(\mathsf{d}) \left[\begin{array}{c} 2\\1 \end{array} \right], \left[\begin{array}{c} 4\\1 \end{array} \right]$

These are two vectors, and they are clearly independent (why?!). Hence, they are a basis of \mathbb{R}^2 . [Note that, in particular, this implies that, without further computations, $\operatorname{span}\left\{\begin{bmatrix}2\\1\end{bmatrix},\begin{bmatrix}4\\1\end{bmatrix}\right\} = \mathbb{R}^2$.]



Any basis of \mathbb{R}^2 has to have two vectors. Three vectors cannot constitute a basis for \mathbb{R}^2 . [Note that we have already learned that three vectors in \mathbb{R}^2 cannot be independent.]

[Further note that $\operatorname{span}\left\{ \begin{bmatrix} 2\\1 \end{bmatrix}, \begin{bmatrix} 4\\1 \end{bmatrix}, \begin{bmatrix} 6\\1 \end{bmatrix} \right\} = \mathbb{R}^2$, so these vectors span, but they are not a basis precisely because of the lack of independence. Independence means that there is no redundancy in the spanning vectors. Here, the third vector is redundant: $\operatorname{span}\left\{ \begin{bmatrix} 2\\1 \end{bmatrix}, \begin{bmatrix} 4\\1 \end{bmatrix}, \begin{bmatrix} 6\\1 \end{bmatrix} \right\} = \operatorname{span}\left\{ \begin{bmatrix} 2\\1 \end{bmatrix}, \begin{bmatrix} 4\\1 \end{bmatrix}, \begin{bmatrix} 4\\1 \end{bmatrix} \right\}$.]

Example 107. Which of the following sets are a basis for \mathbb{R}^3 ?

 $(\mathsf{a})\left[\begin{array}{c}1\\1\\1\end{array}\right],\left[\begin{array}{c}1\\2\\3\end{array}\right]$

Any basis of \mathbb{R}^3 has to have three vectors. Two vectors cannot constitute a basis for \mathbb{R}^3 .

 $(\mathsf{b}) \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3\\3 \end{bmatrix}, \begin{bmatrix} -1\\1\\2\\2 \end{bmatrix}, \begin{bmatrix} 2\\3\\1 \end{bmatrix}$

Any basis of \mathbb{R}^3 has to have three vectors. Four vectors cannot constitute a basis for \mathbb{R}^3 .

 $(\mathsf{C}) \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} -1\\1\\2 \end{bmatrix}$

These are three vectors, which is the right number for a basis of \mathbb{R}^3 . They form a basis if and only if they are linearly independent (and we are experts in checking that).

ſ	. 1	1	-1^{-1}	$R_2 - R_1 \Rightarrow R_2$	1	1	-1		1	1	-1]
	1	2	1	$R_3 - R_1 \Rightarrow R_3 \longrightarrow R_3$	0	1	2	$R_3 - 2R_2 \Rightarrow R_3 \longrightarrow$	0	1	2
	. 1	3	2		0	2	3	$R_3 - 2R_2 \Rightarrow R_3$	0	0	-1

This (homogeneous) system (we are omitting the zero right-hand side) has no free variables. Hence, the three vectors are independent, and therefore a basis of \mathbb{R}^3 .

 $(\mathsf{d}) \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} -1\\1\\3 \end{bmatrix}$

These are three vectors, which is the right number for a basis of \mathbb{R}^3 . They form a basis if and only if they are linearly independent (and we are experts in checking that).

 $\begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & 1 \\ 1 & 3 & 3 \end{bmatrix} \xrightarrow{R_2 - R_1 \Rightarrow R_2}_{\sim \rightarrow R_3} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \xrightarrow{R_3 - 2R_2 \Rightarrow R_3} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

This (homogeneous) system (we are omitting the zero right-hand side) does have a free variable. Hence, the three vectors are dependent, and therefore not a basis of \mathbb{R}^3 .

[By solving the system, we find the dependence relation $3\begin{bmatrix} 1\\1\\1\end{bmatrix} - 2\begin{bmatrix} 1\\2\\3\end{bmatrix} + 1\begin{bmatrix} -1\\1\\3\end{bmatrix} = 0.]$