

Math 415 - Midterm 1

Thursday, September 25, 2014

Circle your section:

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Name:

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Problem 0. [1 point] Write down the number of your discussion section (for instance, AD2 or ADH) and the first name of your TA (Allen, Anton, Babak, Mahmood, Michael, Nathan, Tigran, Travis).

Section:	TA:
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To be completed by the grader:

0	1	2	3	4	5	Shorts	Σ
/1	/11	/15	/15	/12	/8	/21	/83

Good luck!

Problem 1. Let

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 2 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}.$$

(a) [8 points] Determine A^{-1} .

(b) [3 points] Using A^{-1} , solve $A\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.

Solution 1. (a) Using the Gauss–Jordan method, we find:

$$\begin{aligned} \begin{pmatrix} 0 & 1 & 1 & 1 & 0 & 0 \\ 2 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{pmatrix} &\xrightarrow[\sim]{R1 \leftrightarrow R3} \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 1 \\ 2 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \end{pmatrix} \\ &\xrightarrow[\sim]{R2 \rightarrow R2 - 2R1} \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & -1 & -2 & 0 & 1 & -2 \\ 0 & 1 & 1 & 1 & 0 & 0 \end{pmatrix} \\ &\xrightarrow[\sim]{R3 \rightarrow R3 + R2} \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & -1 & -2 & 0 & 1 & -2 \\ 0 & 0 & -1 & 1 & 1 & -2 \end{pmatrix} \\ &\xrightarrow[\sim]{\begin{matrix} R2 \rightarrow -R2 \\ R3 \rightarrow -R3 \end{matrix}} \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 & -1 & 2 \\ 0 & 0 & 1 & -1 & -1 & 2 \end{pmatrix} \\ &\xrightarrow[\sim]{\begin{matrix} R1 \rightarrow R1 - R3 \\ R2 \rightarrow R2 - 2R3 \end{matrix}} \begin{pmatrix} 1 & 1 & 0 & 1 & 1 & -1 \\ 0 & 1 & 0 & 2 & 1 & -2 \\ 0 & 0 & 1 & -1 & -1 & 2 \end{pmatrix} \\ &\xrightarrow[\sim]{R1 \rightarrow R1 - R2} \begin{pmatrix} 1 & 0 & 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & 2 & 1 & -2 \\ 0 & 0 & 1 & -1 & -1 & 2 \end{pmatrix} \end{aligned}$$

Hence,

$$A^{-1} = \begin{pmatrix} -1 & 0 & 1 \\ 2 & 1 & -2 \\ -1 & -1 & 2 \end{pmatrix}.$$

(b) We obtain

$$\mathbf{x} = A^{-1} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 1 \\ 2 & 1 & -2 \\ -1 & -1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

[Note that this is actually obvious when thinking in terms of the column picture of the linear system.]

Problem 2. Consider the matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 4 & 4 \\ 1 & 4 & 8 \end{bmatrix}.$$

- (a) [10 points] Calculate the LU decomposition of A .
 (b) [5 points] Solve

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 4 & 4 \\ 1 & 4 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 7 \end{bmatrix}$$

without reducing the augmented matrix, but using the LU decomposition.

Solution 2. (a) We first find U by Gaussian elimination:

$$\begin{aligned} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 4 & 4 \\ 1 & 4 & 8 \end{pmatrix} &\xrightarrow[\underbrace{R3 \rightarrow R3 - R1}]{R2 \rightarrow R2 - R1} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 0 & 3 & 7 \end{pmatrix} \\ &\xrightarrow{\underbrace{R3 \rightarrow R3 - R2}} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 0 & 0 & 4 \end{pmatrix} \end{aligned}$$

We determine the matrix L from the row operations performed to get the LU decomposition

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 4 & 4 \\ 1 & 4 & 8 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 0 & 0 & 4 \end{pmatrix}.$$

- (b) We solve $A\mathbf{x} = \mathbf{b}$ by first solving $L\mathbf{c} = \mathbf{b}$ via forward substitution. We find

$$\begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \mathbf{c} = \begin{pmatrix} 3 \\ 3 \\ 7 \end{pmatrix} \implies \mathbf{c} = \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix}.$$

Finally, we solve $U\mathbf{x} = \mathbf{c}$ via backward substitution.

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 3 & 3 \\ 0 & 0 & 4 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix} \implies \mathbf{x} = \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix}.$$

Problem 3. Consider the following system of linear equations:

$$\begin{array}{cccccc} x_1 & -2x_2 & +x_3 & & = & 1 \\ -x_1 & +2x_2 & +x_3 & +2x_4 & = & 1 \\ -2x_1 & +4x_2 & +4x_3 & +6x_4 & = & 4 \end{array}$$

- (a) [2 points] Write down the augmented matrix corresponding to this system.
 (b) [7 points] Determine the row reduced echelon form of the augmented matrix.
 (c) [6 points] Use your result in (b) to find a parametric description of the set of solutions to the system of linear equations.

Solution 3. (a) The augmented matrix is

$$\left(\begin{array}{ccccc} 1 & -2 & 1 & 0 & 1 \\ -1 & 2 & 1 & 2 & 1 \\ -2 & 4 & 4 & 6 & 4 \end{array} \right).$$

(b) Gauss–Jordan elimination produces:

$$\begin{array}{l} \left(\begin{array}{ccccc} 1 & -2 & 1 & 0 & 1 \\ -1 & 2 & 1 & 2 & 1 \\ -2 & 4 & 4 & 6 & 4 \end{array} \right) \begin{array}{l} \xrightarrow[R3 \rightarrow R3 + 2R1]{R2 \rightarrow R2 + R1} \\ \\ \end{array} \left(\begin{array}{ccccc} 1 & -2 & 1 & 0 & 1 \\ 0 & 0 & 2 & 2 & 2 \\ 0 & 0 & 6 & 6 & 6 \end{array} \right) \\ \\ \begin{array}{l} \xrightarrow[R3 \rightarrow R3 - 3R2]{} \\ \\ \end{array} \left(\begin{array}{ccccc} 1 & -2 & 1 & 0 & 1 \\ 0 & 0 & 2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \\ \\ \begin{array}{l} \xrightarrow[R2 \rightarrow \frac{1}{2}R2]{} \\ \\ \end{array} \left(\begin{array}{ccccc} 1 & -2 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \\ \\ \begin{array}{l} \xrightarrow[R1 \rightarrow R1 - R2]{} \\ \\ \end{array} \left(\begin{array}{ccccc} 1 & -2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \end{array}$$

Hence, the row reduced echelon form is

$$\left(\begin{array}{ccccc} 1 & -2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right).$$

- (c) The variables x_2 and x_4 are free, and we find the parametric description of the solutions as follows:

$$\begin{cases} x_1 = 2x_2 + x_4 \\ x_2 \text{ is free} \\ x_3 = 1 - x_4 \\ x_4 \text{ is free} \end{cases}$$

Optionally, and equivalently, we can write the set of solutions as

$$\left\{ \left(\begin{array}{c} 2x_2 + x_4 \\ x_2 \\ 1 - x_4 \\ x_4 \end{array} \right) : x_2, x_4 \text{ in } \mathbb{R} \right\} = \left(\begin{array}{c} 0 \\ 0 \\ 1 \\ 0 \end{array} \right) + \text{span} \left\{ \left(\begin{array}{c} 2 \\ 1 \\ 0 \\ 0 \end{array} \right), \left(\begin{array}{c} 1 \\ 0 \\ -1 \\ 1 \end{array} \right) \right\}.$$

[Note that the final span is the null space of the coefficient matrix.]

Problem 4. Let

$$\mathbf{w} = \begin{bmatrix} 1 \\ h \\ 3h \end{bmatrix}, \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

- (a) [8 points] For which value of h is \mathbf{w} a linear combination of \mathbf{v}_1 and \mathbf{v}_2 ?
(b) [4 points] For the value of h found in (a), write down the linear combination of \mathbf{v}_1 and \mathbf{v}_2 which gives \mathbf{w} .

Solution 4. (a) \mathbf{w} is a linear combination of \mathbf{v}_1 and \mathbf{v}_2 if and only if the system with augmented matrix

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & h \\ 1 & 3 & 3h \end{pmatrix}$$

is consistent. From the echelon form

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & h \\ 1 & 3 & 3h \end{pmatrix} \xrightarrow[\underset{\sim}{R3 \rightarrow R3 - R1}]{R2 \rightarrow R2 - R1} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & h - 1 \\ 0 & 2 & 3h - 1 \end{pmatrix} \xrightarrow{R3 \rightarrow R3 - 2R2} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & h - 1 \\ 0 & 0 & h + 1 \end{pmatrix}$$

we find that the system is consistent if and only if $h = -1$.

Hence, \mathbf{w} is a linear combination of \mathbf{v}_1 and \mathbf{v}_2 if and only if $h = -1$.

- (b) The coefficients of such a linear combinations are given by the solutions of the system. In the case $h = -1$, this system has augmented matrix

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & h - 1 \\ 0 & 0 & h + 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{pmatrix}.$$

A simple backward substitution gives the solution $x_2 = -2$ and $x_1 = 3$. The corresponding linear combination is

$$3\mathbf{v}_1 - 2\mathbf{v}_2 = \mathbf{w}.$$

Problem 5. [8 points] Determine which of the following sets are a subspace of the vector space of all 2×2 matrices. In each case, give a short reason.

(a) $W_1 = \left\{ \begin{bmatrix} 2a & b \\ b & 3a \end{bmatrix} : a, b \text{ in } \mathbb{R} \right\}$

(b) $W_2 = \left\{ \begin{bmatrix} 2a & b \\ b & 3a \end{bmatrix} : a, b \text{ in } \mathbb{R} \text{ and } a + b = 1 \right\}$

Solution 5. (a) W_1 is a subspace because we can write it as a span:

$$W_1 = \text{span} \left\{ \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right\}$$

(b) W_2 is not a subspace because it does not contain the zero vector. Indeed, if

$$\begin{pmatrix} 2a & b \\ b & 3a \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix},$$

then $a = 0$ and $b = 0$. But this contradicts $a + b = 1$.

SHORT ANSWERS
[21 points overall, 3 points each]

Instructions: The following problems have a short answer. No reason needs to be given. If the problem is multiple choice, circle the correct answer (there is always exactly one correct answer).

Short Problem 1. Let $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix}$. Compute $A^T A$.

$$A^T A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$$

Short Problem 2. Let A be a matrix such that, for every $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ in \mathbb{R}^3 , $A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2y \\ x \\ x - z \end{bmatrix}$.

Then, what is A ?

$$A = \begin{pmatrix} 0 & 2 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & -1 \end{pmatrix}$$

Short Problem 3. Let C be a 3×4 matrix such that C has two pivot columns, and let \mathbf{d} be a vector in \mathbb{R}^3 . Is it true that, if the equation $C\mathbf{x} = \mathbf{d}$ has a solution, then it has infinitely many solutions?

- (a) True.
- (b) False.
- (c) Unable to determine.

This is true, because there is a free variable (actually, it is two). Hence, the system has infinitely many solutions unless it is inconsistent.

Short Problem 4. Let

$$A = \begin{bmatrix} a & a+1 \\ a+1 & a \end{bmatrix}.$$

For which choice(s) of a is the matrix A *not* invertible?

A 2×2 matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is not invertible if and only if $ad - bc = 0$. Since $a^2 - (a+1)^2 = -2a - 1$, A is not invertible if and only if $a = -\frac{1}{2}$.

Short Problem 5. There is one vector which every subspace of \mathbb{R}^2 has to contain. Which vector is that?

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Short Problem 6. Let W_1 be the set of all polynomials $p(t)$ which have a zero at $t = 1$ (that is, $p(1) = 0$), and let W_0 be the set of all polynomials $p(t)$ which have a zero at $t = 0$. Are these sets subspaces of the vector space of all polynomials?

- (a) Both W_0 and W_1 are subspaces.
- (b) Only W_0 is a subspace.
- (c) Only W_1 is a subspace.
- (d) Neither W_0 nor W_1 are subspaces.

If two polynomials have a zero at $t = t_0$ for some fixed t_0 in \mathbb{R} , then the sum of these polynomials has a zero at $t = t_0$ as well. Likewise, for scaling. Hence, both W_0 and W_1 are subspaces.

Short Problem 7. Let $W = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \right\}$. Which of the following is true?

- (a) W is empty.
- (b) W is a line.
- (c) W is a plane.
- (d) W is all of \mathbb{R}^3 .

This is a plane.