Systems of linear DEs: the inhomogeneous case

Recall that any linear DE can be transformed into a first-order system. Hence, any linear DE (or any system of linear DEs) can be written as

$$\boldsymbol{y}' = A(t)\,\boldsymbol{y} + \boldsymbol{f}(t).$$

Note. The DE is allowed to have nonconstant coefficients (A depends on t). On the other hand, this is an autonomous DE (those for which we can analyze phase portraits) only if $A(t)$ and $\boldsymbol{f}(t)$ actually don't depend on t.

The same arguments as for Theorem 94 with the same result apply to systems of linear equations!

Recall that we showed in Theorem 94 that $y' = a(t)y + f(t)$ has the particular solution

$$y_p(t) = y_h(t)\int \frac{f(t)}{y_h(t)}\mathrm{d}t,$$

where $y_h(t) = e^{\int a(t)\mathrm{d}t}$ is a solution to the homogeneous equation $y' = a(t)y$.

Theorem 96. (variation of constants) $\boldsymbol{y}' = A(t)\,\boldsymbol{y} + \boldsymbol{f}(t)$ has the particular solution

$$\boldsymbol{y}_p(t) = \Phi(t)\int \Phi(t)^{-1}\boldsymbol{f}(t)\mathrm{d}t,$$

where $\Phi(t)$ is a fundamental matrix solution to $\boldsymbol{y}' = A(t)\,\boldsymbol{y}$.

Proof. Since the general solution of the homogeneous equation $\boldsymbol{y}' = A(t)\,\boldsymbol{y}$ is $\boldsymbol{y}_h = \Phi(t)\boldsymbol{c}$, we are going to vary the constant $\boldsymbol{c}$ and look for a particular solution of the form $\boldsymbol{y}_p = \Phi(t)\boldsymbol{c}(t)$. Plugging into the DE, we get:

$$\boldsymbol{y}_p' = \Phi'\boldsymbol{c} + \Phi\boldsymbol{c}' = A\Phi\boldsymbol{c} + \Phi\boldsymbol{c}' \overset{!}{=} A\boldsymbol{y}_p + \boldsymbol{f} = A\Phi\boldsymbol{c} + \boldsymbol{f}$$

For the first equality, we used the matrix version of the usual product rule (which holds since differentiation is defined entry-wise). For the second equality, we used $\Phi' = A\Phi$.

Hence, $\boldsymbol{y}_p = \Phi(t)\boldsymbol{c}(t)$ is a particular solution if and only if $\Phi\boldsymbol{c}' = \boldsymbol{f}$.

The latter condition means $\boldsymbol{c}' = \Phi^{-1}\boldsymbol{f}$ so that $\boldsymbol{c} = \int \Phi(t)^{-1}\boldsymbol{f}(t)\mathrm{d}t$, which gives the claimed formula for $\boldsymbol{y}_p$. □

Example 97. Find a particular solution to $\boldsymbol{y}' = \begin{bmatrix} 2 & 3 \\ 2 & 1 \end{bmatrix}\boldsymbol{y} + \begin{bmatrix} 0 \\ -2e^{3t} \end{bmatrix}$.

Solution. First, we determine (do it!) a fundamental matrix solution for $\boldsymbol{y}' = \begin{bmatrix} 2 & 3 \\ 2 & 1 \end{bmatrix}\boldsymbol{y}$: $\Phi(x) = \begin{bmatrix} e^{-t} & 3e^{4t} \\ -e^{-t} & 2e^{4t} \end{bmatrix}$

Using $\det(\Phi(t)) = 5e^{3t}$, we find $\Phi(t)^{-1} = \frac{1}{5}\begin{bmatrix} 2e^{t} & -3e^{t} \\ e^{-4t} & e^{-4t} \end{bmatrix}$.

Hence, $\Phi(t)^{-1}\boldsymbol{f}(t) = \frac{2}{5}\begin{bmatrix} 3e^{4t} \\ -e^{-t} \end{bmatrix}$ and $\int \Phi(t)^{-1}\boldsymbol{f}(t)\mathrm{d}x = \frac{2}{5}\begin{bmatrix} 3/4e^{4t} \\ e^{-t} \end{bmatrix}$.

By variation of constants, $\boldsymbol{y}_p(t) = \Phi(t)\int \Phi(t)^{-1}\boldsymbol{f}(t)\mathrm{d}t = \begin{bmatrix} e^{-t} & 3e^{4t} \\ -e^{-t} & 2e^{4t} \end{bmatrix}\frac{2}{5}\begin{bmatrix} 3/4e^{4t} \\ e^{-t} \end{bmatrix} = \begin{bmatrix} 3/2 \\ 1/2 \end{bmatrix}e^{3t}$.

Comment. Note that the solution is of the form that we anticipate from the method of undetermined coefficients (which we only discussed in the case of a single DE but which works similarly for systems).

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Sage. Here is a way to have Sage do these computations for us. Keep in mind that we can choose $\Phi(t) = e^{At}$.

```
>>> s, t = var('s, t')
>>> A = matrix([[2,3],[2,1]])
>>> y = exp(A*t)*integrate(exp(-A*t)*vector([0,-2*e^(3*t)]), t)
>>> y.simplify_full()
```

$$\left(\frac{3}{2}e^{(3t)}, \frac{1}{2}e^{(3t)}\right)$$

In the special case that $\Phi(t) = e^{At}$, some things become easier. For instance, $\Phi(t)^{-1} = e^{-At}$. In that case, we can explicitely write down solutions to IVPs:

- $\boldsymbol{y}' = A\boldsymbol{y}$, $\boldsymbol{y}(0) = \boldsymbol{c}$ has (unique) solution $\boldsymbol{y}(t) = e^{At}\boldsymbol{c}$.
- $\boldsymbol{y}' = A\boldsymbol{y} + \boldsymbol{f}(t)$, $\boldsymbol{y}(0) = \boldsymbol{c}$ has (unique) solution $\boldsymbol{y}(t) = e^{At}\boldsymbol{c} + e^{At}\int_0^t e^{-As}\boldsymbol{f}(s)\mathrm{d}s$.

Example 98. Let $A = \begin{bmatrix} 1 & 2 \\ -1 & 4 \end{bmatrix}$.

(a) Determine e^{At}.

(b) Solve $\boldsymbol{y}' = A\boldsymbol{y}$, $\boldsymbol{y}(0) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

(c) Solve $\boldsymbol{y}' = A\boldsymbol{y} + \begin{bmatrix} 0 \\ 2e^t \end{bmatrix}$, $\boldsymbol{y}(0) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

Solution.

(a) By proceeding as in Example 69 (do it!), we find $e^{At} = \begin{bmatrix} 2e^{2t} - e^{3t} & -2e^{2t} + 2e^{3t} \\ e^{2t} - e^{3t} & -e^{2t} + 2e^{3t} \end{bmatrix}$.

(b) $\boldsymbol{y}(t) = e^{At}\begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2e^{2t} + 3e^{3t} \\ -e^{2t} + 3e^{3t} \end{bmatrix}$

(c) $\boldsymbol{y}(t) = e^{At}\begin{bmatrix} 1 \\ 2 \end{bmatrix} + e^{At}\int_0^t e^{-As}\boldsymbol{f}(s)\mathrm{d}s$. We compute:

$\int_0^t e^{-As}\boldsymbol{f}(s)\mathrm{d}s = \int_0^t \begin{bmatrix} 2e^{-2s} - e^{-3s} & -2e^{-2s} + 2e^{-3s} \\ e^{-2s} - e^{-3s} & -e^{-2s} + 2e^{-3s} \end{bmatrix}\begin{bmatrix} 0 \\ 2e^s \end{bmatrix}\mathrm{d}s = \int_0^t \begin{bmatrix} -4e^{-s} + 4e^{-2s} \\ -2e^{-s} + 4e^{-2s} \end{bmatrix}\mathrm{d}s = \begin{bmatrix} 4e^{-t} - 2e^{-2t} - 2 \\ 2e^{-t} - 2e^{-2t} \end{bmatrix}$

Hence, $e^{At}\int_0^t e^{-As}\boldsymbol{f}(s)\mathrm{d}s = \begin{bmatrix} 2e^{2t} - e^{3t} & -2e^{2t} + 2e^{3t} \\ e^{2t} - e^{3t} & -e^{2t} + 2e^{3t} \end{bmatrix}\begin{bmatrix} 4e^{-t} - 2e^{-2t} - 2 \\ 2e^{-t} - 2e^{-2t} \end{bmatrix} = \begin{bmatrix} 2e^t - 4e^{2t} + 2e^{3t} \\ -2e^{2t} + 2e^{3t} \end{bmatrix}$.

Finally, $\boldsymbol{y}(t) = \begin{bmatrix} -2e^{2t} + 3e^{3t} \\ -e^{2t} + 3e^{3t} \end{bmatrix} + \begin{bmatrix} 2e^t - 4e^{2t} + 2e^{3t} \\ -2e^{2t} + 2e^{3t} \end{bmatrix} = \begin{bmatrix} 2e^t - 6e^{2t} + 5e^{3t} \\ -3e^{2t} + 5e^{3t} \end{bmatrix}$.

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Sage. Here is how we can let Sage do these computations for us:

```
>>> s, t = var('s, t')
>>> A = matrix([[1,2],[-1,4]])
>>> y = exp(A*t)*vector([1,2]) + exp(A*t)*integrate(exp(-A*s)*vector([0,2*e^s]), s,0,t)
>>> y.simplify_full()
```

$(5\,e^{(3\,t)} - 6\,e^{(2\,t)} + 2\,e^{t},\, 5\,e^{(3\,t)} - 3\,e^{(2\,t)})$

Comment. Can you see that the solution is of the form that we anticipate from the method of undetermined coefficients?
Indeed, $\boldsymbol{y}(t) = \boldsymbol{y}_p(t) + \boldsymbol{y}_h(t)$ where the simplest particular solution is $\boldsymbol{y}_p(t) = \begin{bmatrix} 2e^t \\ 0 \end{bmatrix}$.

Example 99. In Example 91, we derived the IVP $\frac{\mathrm{d}}{\mathrm{d}t}\boldsymbol{y} = \begin{bmatrix} -3 & 2 \\ 3 & -8 \end{bmatrix}\boldsymbol{y} + \begin{bmatrix} 27 \\ 0 \end{bmatrix}$, $\boldsymbol{y}(0) = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$. Solve it using our new tools.

Solution. This is an IVP that we can solve (with some work). Do it! For instance, we can apply variation of constants. (Alternatively, leverage our particular solution from the previous part!) Skipping most work, we find:

- If $A = \begin{bmatrix} -3 & 2 \\ 3 & -8 \end{bmatrix}$, then $e^{At} = \frac{1}{7}\begin{bmatrix} e^{-9t} + 6e^{-2t} & -2e^{-9t} + 2e^{-2t} \\ -3e^{-9t} + 3e^{-2t} & 6e^{-9t} + e^{-2t} \end{bmatrix}$
- $\boldsymbol{y} = e^{At}\begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^{At}\int_0^t e^{-As}\begin{bmatrix} 27 \\ 0 \end{bmatrix}\mathrm{d}s = \frac{1}{7}\begin{bmatrix} e^{-9t} + 6e^{-2t} \\ -3e^{-9t} + 3e^{-2t} \end{bmatrix} + \frac{3}{14}e^{At}\begin{bmatrix} 2e^{9t} + 54e^{2t} - 56 \\ -6e^{9t} + 27e^{2t} - 21 \end{bmatrix}$
  $= \begin{bmatrix} 12 - 9e^{-2t} \\ 4.5 - 4.5e^{-2t} \end{bmatrix}$

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