Sketch of Lecture 49

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Review. Eigenvalues and eigenfunctions of $y'' + \lambda y = 0$, y(0) = 0, y(L) = 0.

Example 186. Suppose that a rod of length L is compressed by a force P. We model the shape of the rod by a function y(x) on the interval [0, L]. The theory of elasticity predicts that, under some simplifying assumptions, y should satisfy EIy'' + Py = 0, y(0) = 0, y(L) = 0.

Here, EI is a constant modeling the inflexibility of the rod (E, known as Young's modulus, depends on the material, and I depends on the shape of cross-sections (it is the area moment of inertia)).

In other words, $y'' + \lambda y = 0$, y(0) = 0, y(L) = 0, with $\lambda = \frac{P}{EI}$. The fact that there is no nonzero solution unless $\lambda = \left(\frac{\pi n}{L}\right)^2$ for some n = 1, 2, 3, ..., means that buckling can only occur if $P = \left(\frac{\pi n}{L}\right)^2 EI$. In particular, no buckling occurs for forces less than $\frac{\pi^2 EI}{L^2}$. This is known as the critical load (or Euler load) of the rod.

The heat equation

We wish to describe one-dimensional heat flow³³. Let u(x, t) describe the temperature at time t at position x. If we model a heated rod of length L, then $x \in [0, L]$.

Note that u(x, t) depends on two variables. When taking derivatives, we will use the notations $u_t = \frac{\partial}{\partial t}u$ and $u_{xx} = \frac{\partial^2}{\partial t^2}u$ for first and higher derivatives.

Experience tells us that heat flows from warmer to cooler areas and has an averaging effect. Make a sketch of some temperature profile u(x,t) for fixed t. Then as t increases, we expect maxima (where $u_{xx} < 0$) of that profile to flatten out (so $u_t < 0$); similarly, minima (where $u_{xx} > 0$) should go up (so $u_t > 0$). The simplest relationship between u_t and u_{xx} which conforms with our expectation is $u_t = k u_{xx}$, with k > 0. That's the heat equation.

Note that the heat equation is a linear and homogeneous partial differential equation.

In particular, the principle of superposition holds: if u_1 and u_2 solve the heat equation, then so does $c_1u_1 + c_2u_2$.

Remark 187. In higher dimensions, the heat equation takes the form $u_t = k(u_{xx} + u_{yy})$ or $u_t = k(u_{xx} + u_{yy} + u_{zz})$. Note that $\Delta u = u_{xx} + u_{yy} + u_{zz}$ is the Laplace operator³⁴.

Example 188. Note that u(x,t) = ax + b solves the heat equation.

Let us think about what is needed to describe a unique solution of the heat equation.

Example 189. To get a feeling, let us find some other solutions to $u_t = u_{xx}$ (for starters, k = 1).

For instance, $u(x,t) = e^t e^x$ is a solution. Not a very interesting one for modeling heat flow because it increases exponentially in time.

More interesting are $u(x,t) = e^{-t}\cos(x)$ and $u(x,t) = e^{-t}\sin(x)$. More generally, $e^{-n^2t}\cos(nx)$ and $e^{-n^2t}\sin(nx)$ are solutions. This actually reveals a strategy for solving the heat equation with conditions such as $u_t = u_{xx}$, u(0,t) = 0, u(L,t) = 0, u(x,0) = f(x).

Namely, the solutions $u_n(x, t) = e^{-n^2 t} \sin(nx)$ all satisfy u(0, t) = 0, $u(\pi, t) = 0$. On the other hand, $u_n(x, 0) = \sin(nx)$. To find u(x,t) such that u(x,0) = f(x), we thus only need to write f(x) as a Fourier (sine) series.

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^{33.} If this sounds very specialized, it might help to know that the heat equation is also used, for instance, in probability (Brownian motion), financial math (Black-Scholes), or chemical processes (diffusion equation).

^{34.} The Laplacian Δu is also often written as $\Delta u = \nabla^2 u$. The operator $\nabla = (\partial/\partial x, \partial/\partial y)$ is pronounced "nabla" (Greek for a certain harp) or "del" (Persian for heart), and ∇^2 is short for the inner product $\nabla \cdot \nabla$.