

## Boundary value problems and partial differential equations

### Endpoint problems and eigenvalues

**Example 181.** The IVP (initial value problem)  $y'' + 4y = 0$ ,  $y(0) = 0$ ,  $y'(0) = 0$  has the unique solution  $y(x) = 0$ . ◇

Initial value problems are often used when the problem depends on time. Then, as we know for instance for the motion of a pendulum,  $y(0)$  and  $y'(0)$  describe the initial configuration at  $t = 0$ . For problems which instead depend on spatial variables, such as position, it may be natural to specify values at positions on the boundary (for instance, if  $y(x)$  describes the steady-state temperature of a rod at position  $x$ , we might know the temperature at the two end points).

The next two examples illustrate that such boundary value problem may or may not have unique solutions.

**Example 182.** The BVP (boundary value problem)  $y'' + 4y = 0$ ,  $y(0) = 0$ ,  $y(1) = 0$  has the unique solution  $y(x) = 0$ .

We know that the general solution to the DE is  $y(x) = A \cos(2x) + B \sin(2x)$ . The boundary conditions imply  $y(0) = A \stackrel{!}{=} 0$  and, already using that  $A = 0$ ,  $y(1) = B \sin(2) \stackrel{!}{=} 0$  shows that  $B = 0$  as well. ◇

**Example 183.** The BVP  $y'' + \pi^2 y = 0$ ,  $y(0) = 0$ ,  $y(1) = 0$  is solved by  $y(x) = B \sin(\pi x)$  for any value  $B$ .

This time, the general solution to the DE is  $y(x) = A \cos(\pi x) + B \sin(\pi x)$ . The boundary conditions imply  $y(0) = A \stackrel{!}{=} 0$  and, using that  $A = 0$ ,  $y(1) = B \sin(\pi) \stackrel{!}{=} 0$ . This second condition true for any  $B$ . ◇

It is therefore natural to ask: for which  $\lambda$  does  $y'' + \lambda y = 0$ ,  $y(0) = 0$ ,  $y(L) = 0$  have nonzero solutions? Such solutions are called **eigenfunctions** and  $\lambda$  is the corresponding **eigenvalue**.

**Remark 184.** Compare that to our previous use of the term eigenvalue: given a matrix  $A$ , we asked: for which  $\lambda$  does  $A\mathbf{v} - \lambda\mathbf{v} = 0$  have nonzero solutions  $\mathbf{v}$ ? Such solutions were called **eigenvectors** and  $\lambda$  was the corresponding **eigenvalue**. ◇

**Example 185.** Find all eigenfunctions and eigenvalues of  $y'' + \lambda y = 0$ ,  $y(0) = 0$ ,  $y(L) = 0$ .

Such a problem is called an **eigenvalue problem**.

**Solution.** The solutions of the DE look different in the cases  $\lambda < 0$ ,  $\lambda = 0$ ,  $\lambda > 0$ , so we consider them individually.

$\lambda = 0$ . Then  $y(x) = Ax + B$  and  $y(0) = y(L) = 0$  implies that  $y(x) = 0$ . No eigenfunction here.

$\lambda < 0$ . Write  $\lambda = -\rho^2$ . Then  $y(x) = Ae^{\rho x} + Be^{-\rho x}$ .  $y(0) = A + B \stackrel{!}{=} 0$  implies  $B = -A$ . Using that, we get  $y(L) = A(e^{\rho L} - e^{-\rho L}) \stackrel{!}{=} 0$ . For eigenfunctions we need  $A \neq 0$ , so  $e^{\rho L} = e^{-\rho L}$  which implies  $\rho L = -\rho L$ . This cannot happen since  $\rho \neq 0$  and  $L \neq 0$ . Again, no eigenfunctions in this case.

$\lambda > 0$ . Write  $\lambda = \rho^2$ . Then  $y(x) = A \cos(\rho x) + B \sin(\rho x)$ .  $y(0) = A \stackrel{!}{=} 0$ . Using that,  $y(L) = B \sin(\rho L) \stackrel{!}{=} 0$ . Since  $B \neq 0$  for eigenfunctions, we need  $\sin(\rho L) = 0$ . This happens if  $\rho L = n\pi$  for  $n = 0, 1, 2, \dots$ . Consequently, we do find the eigenfunctions  $y_n(x) = \sin \frac{n\pi x}{L}$ ,  $n = 1, 2, 3, \dots$ , with eigenvalue  $\lambda = \left(\frac{n\pi}{L}\right)^2$ . ◇