

**Review.** Cartesian coordinates and points in three dimensions; distances

**Example 18.** Interpret the following equations (in three-dimensional space) geometrically:

- (a)  $z = 2$
- (b)  $x^2 + y^2 = 1$
- (c)  $x^2 + y^2 = 1, z = 2$
- (d)  $x^2 + y^2 + z^2 = 4$

**Solution.**

(a) This is a plane parallel to the  $xy$ -plane.

Equivalently, we could describe this as a plane perpendicular to the  $z$ -axis.

**Comment.** This is a 2-dimensional object. (1 equation in 3D:  $3 - 1 = 2$ )

(b) [In the  $xy$ -plane, this is just the unit circle.]

In three dimensions, this is (the surface) of a cylinder (or tube of infinite height). Make a sketch!

**Comment.** Again, this is a 2-dimensional object. (1 equation:  $3 - 1 = 2$ )

(c) Geometrically, this is the intersection of our previous two objects. What is left, is a circle in the plane  $z = 2$ .

**Comment.** Now, this is a 1-dimensional object. (2 equations:  $3 - 2 = 1$ )

(d) By our knowledge of distance, we see that these are all the points  $(x, y, z)$  that have distance 2 from the origin. This is called a **sphere**; this one has radius 2 and center  $(0, 0, 0)$ .

**Comment.** Again, this is a 2-dimensional object. (1 equation:  $3 - 1 = 2$ )

A **sphere** of radius  $r$  and center  $(x_0, y_0, z_0)$  is described by

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2.$$

Why? A sphere is the “skin” (surface, to be more professional) of a ball. In this case, these are all the points  $(x, y, z)$  which have distance exactly  $r$  from  $(x_0, y_0, z_0)$ . In equations:  $\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2} = r$

## Vectors

[Physical objects like force or velocity are vectors...]

**Example 19.** Given points  $P_1 = (1, 1)$  and  $P_2 = (3, 2)$ , the **vector**  $\overrightarrow{P_1P_2}$  is the “arrow” connecting the two points. [The vector measures precisely the displacement from  $P_1$  to  $P_2$ .]

- Make a sketch!
- The **component form** of the vector is  $\overrightarrow{P_1P_2} = \langle 3 - 1, 2 - 1 \rangle = \langle 2, 1 \rangle$ .  
At least for a while, we will use the pointy brackets for vectors, just to distinguish them from points.
- If  $O = (0, 0)$  is the origin and  $P$  is the point  $P = (2, 1)$ , then the vector  $\overrightarrow{OP} = \langle 2, 1 \rangle$  is the **same vector** as  $\overrightarrow{P_1P_2}$  (in our sketch, the corresponding arrows are just in different position).

[The book says the vector is in “standard position” if we place its tail at the origin.]

Vectors consist of a **length** and a **direction**.

(more on direction next time)

- The length of  $\mathbf{v} = \langle v_1, v_2 \rangle$  is  $|\mathbf{v}| = \sqrt{v_1^2 + v_2^2}$ .
- Likewise, in 3D, the length of  $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$  is  $|\mathbf{v}| = \sqrt{v_1^2 + v_2^2 + v_3^2}$ .